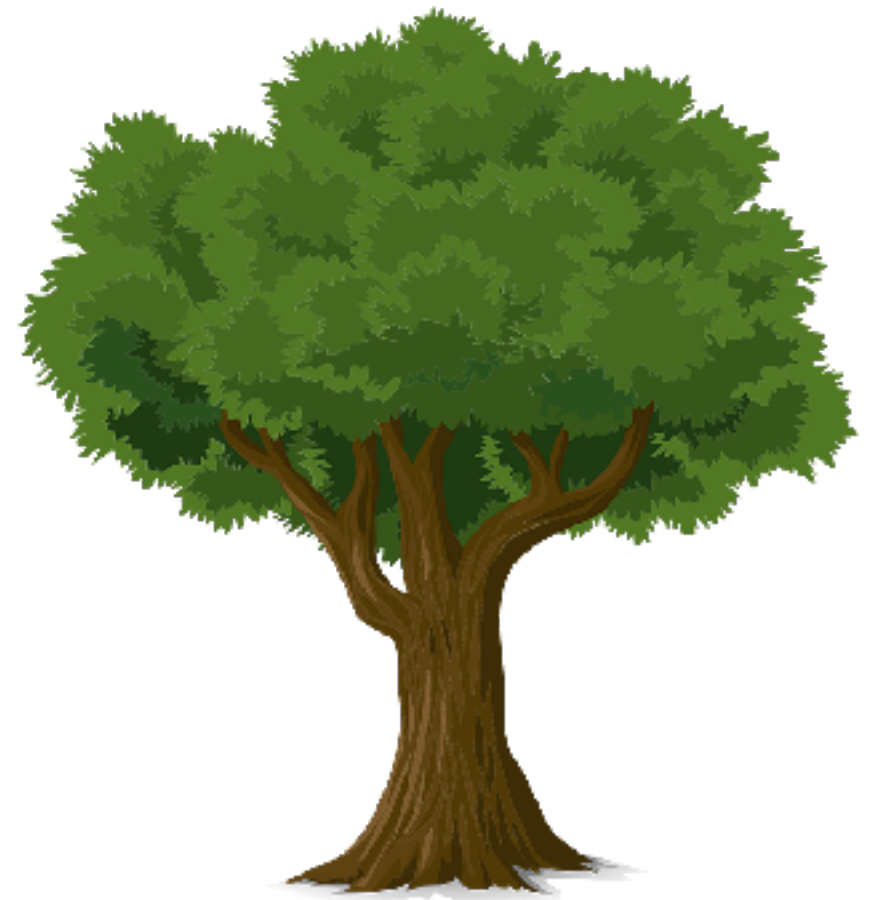


# Parking on Cayley trees

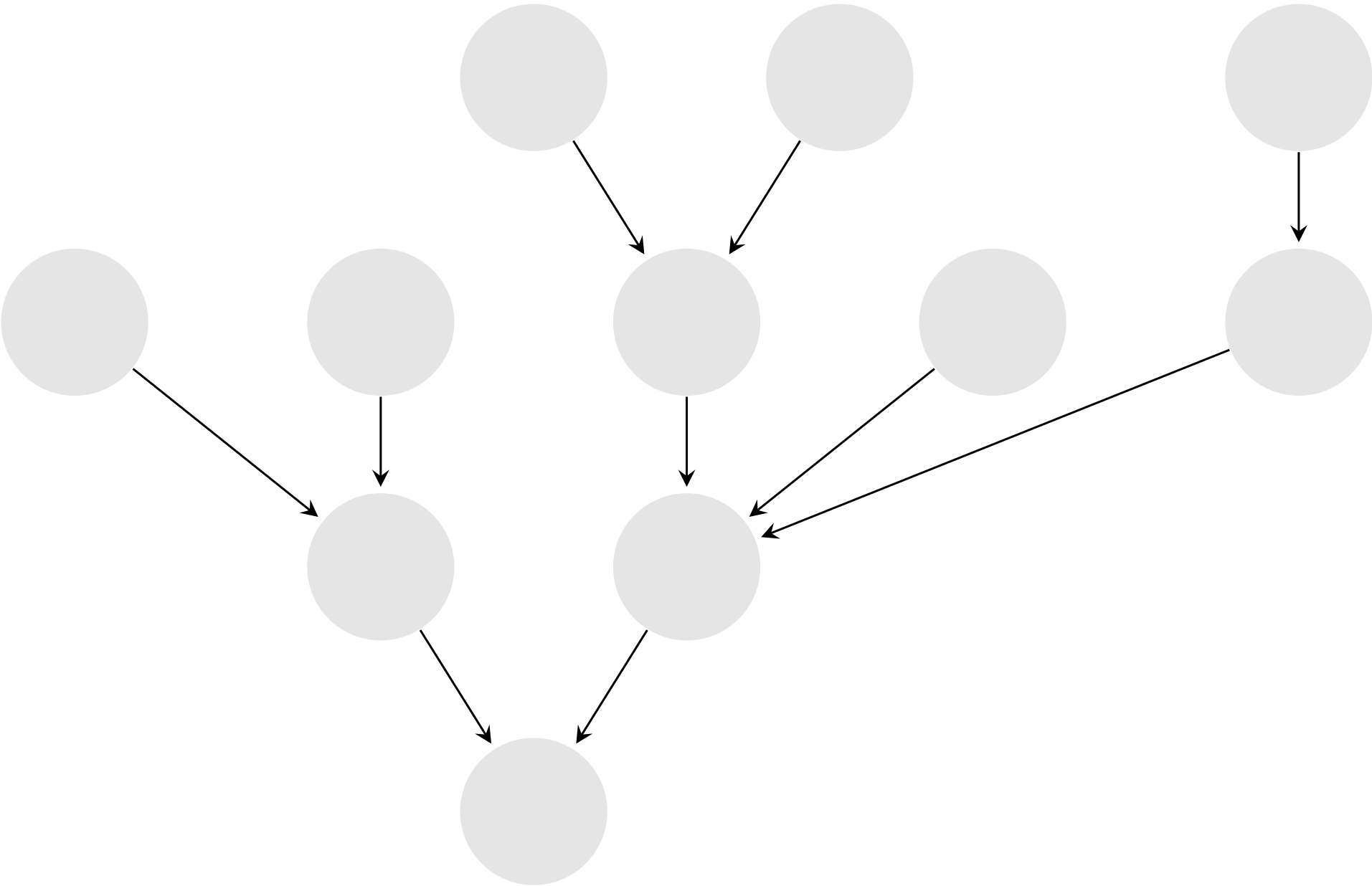
Journées Math-STIC 2024

4<sup>th</sup> October 2024

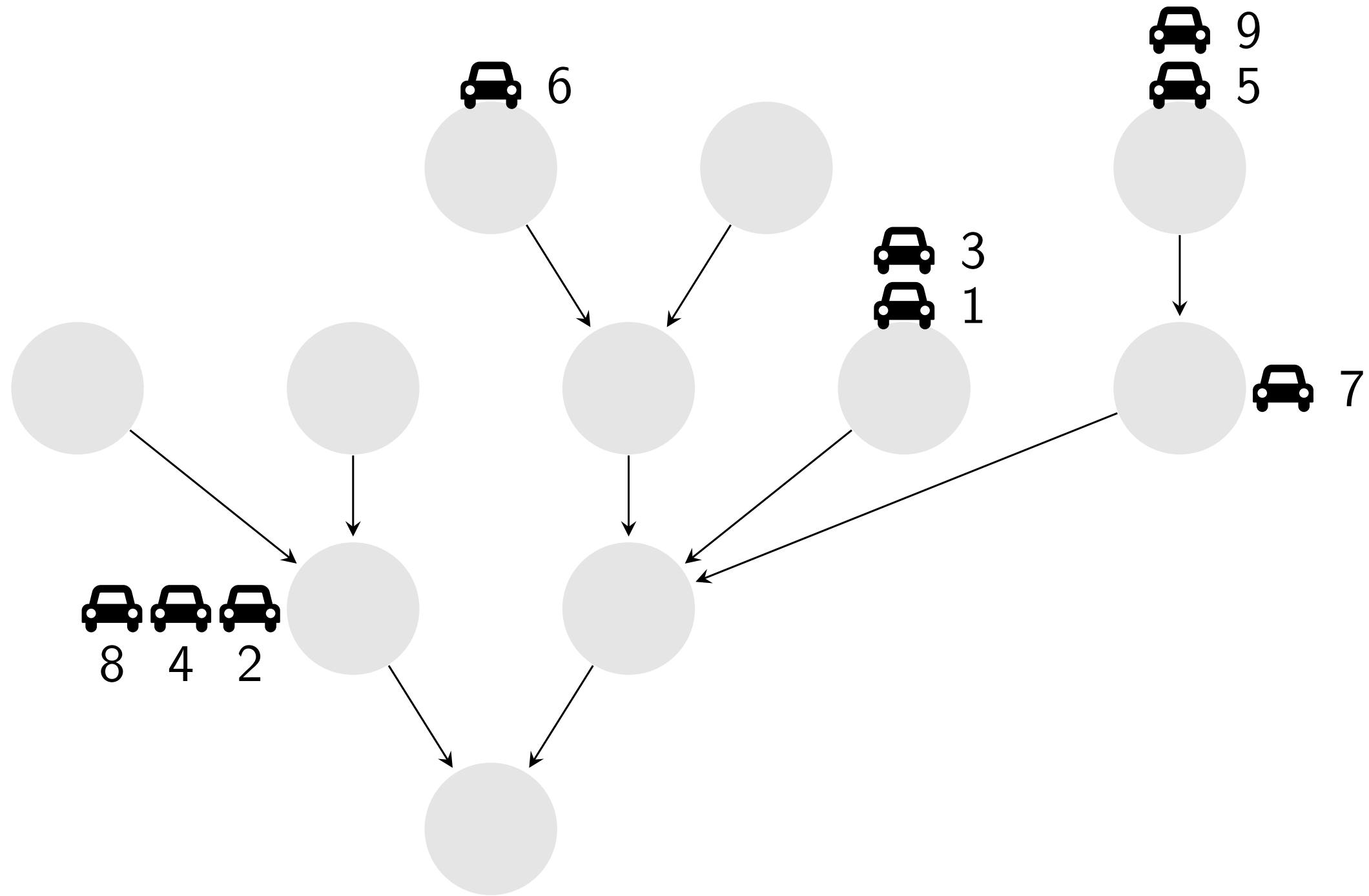
Alice CONTAT



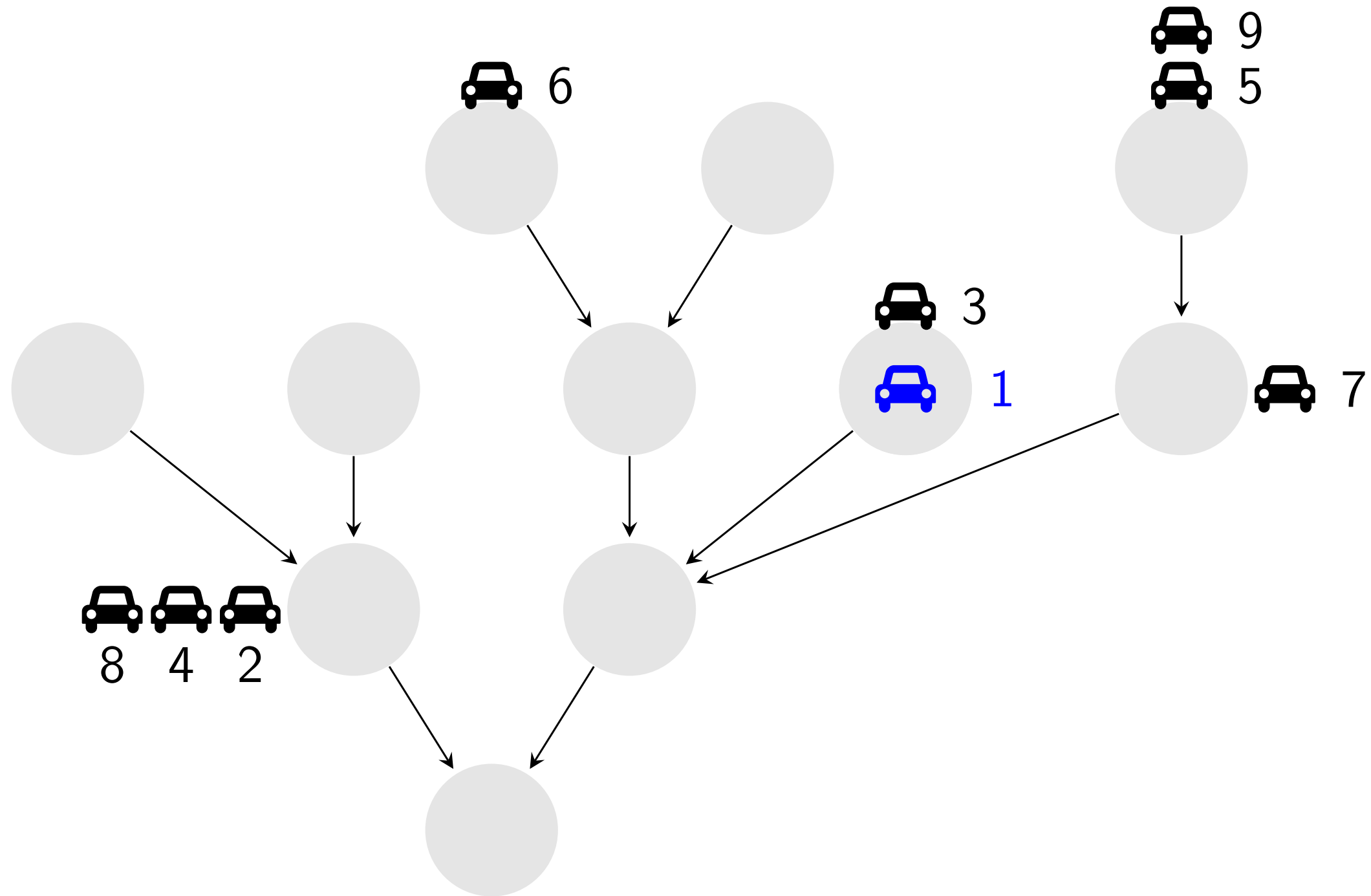
# Parking rules on a tree



# Parking rules on a tree

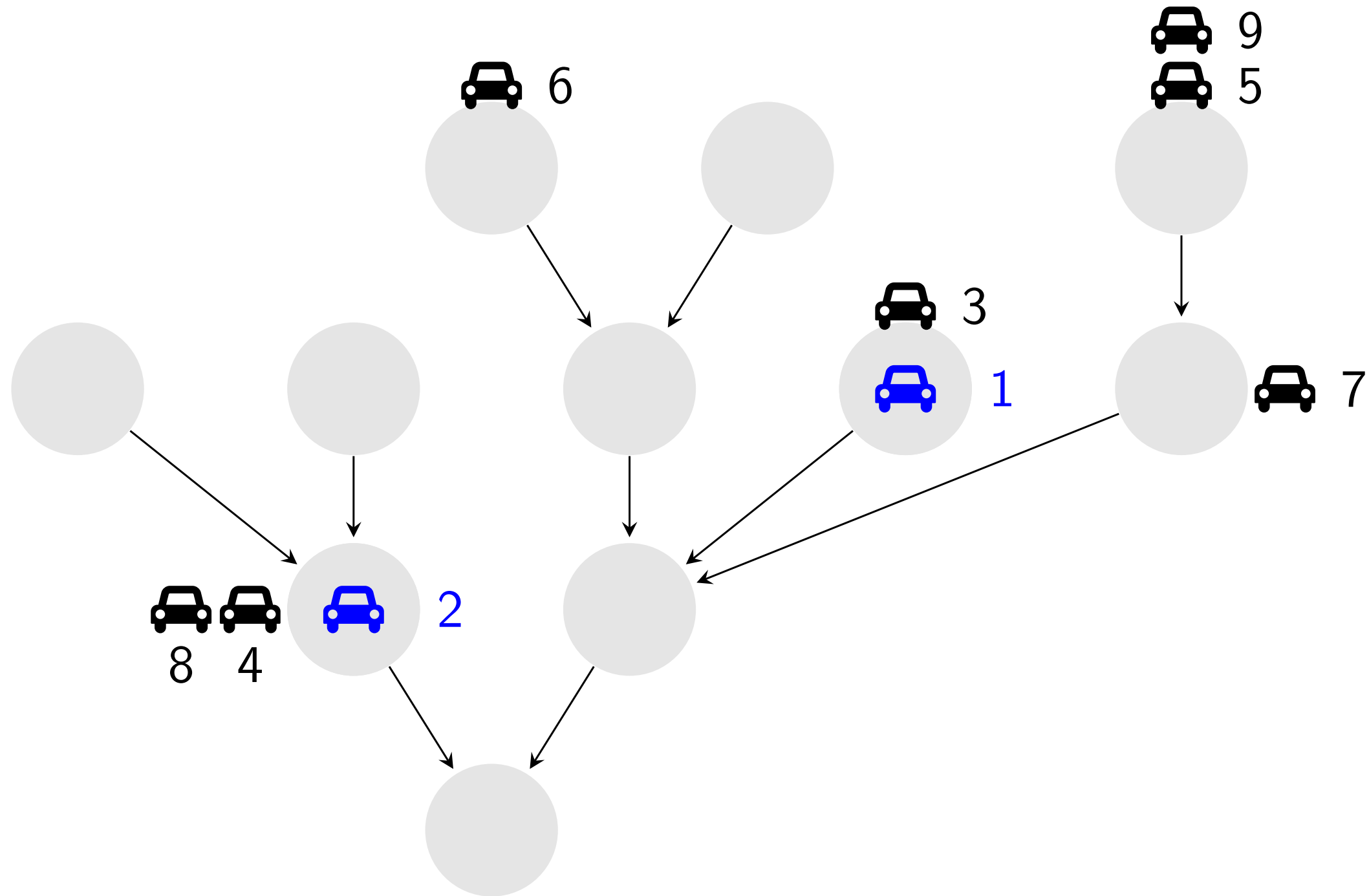


# Parking rules on a tree

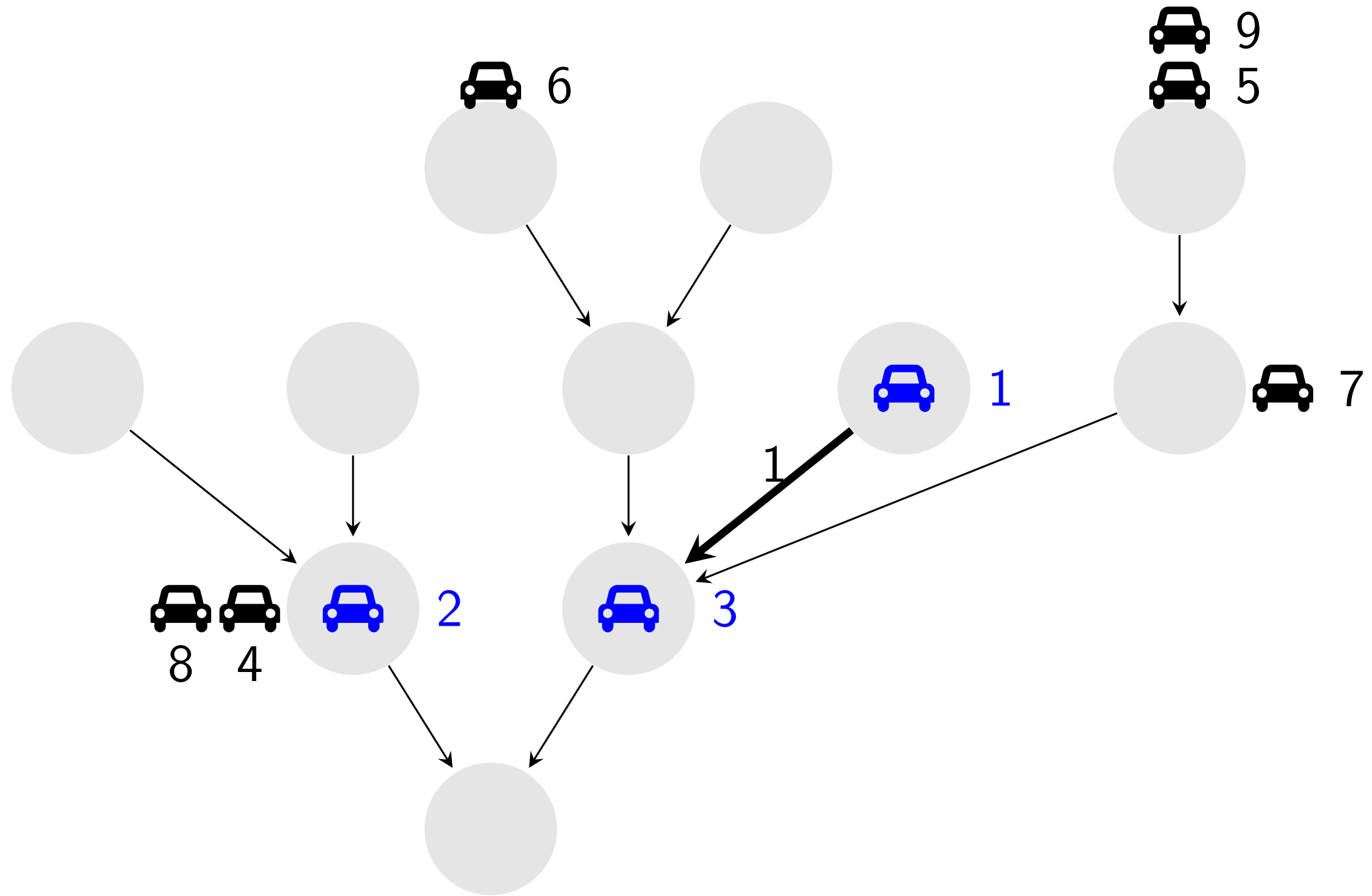




# Parking rules on a tree

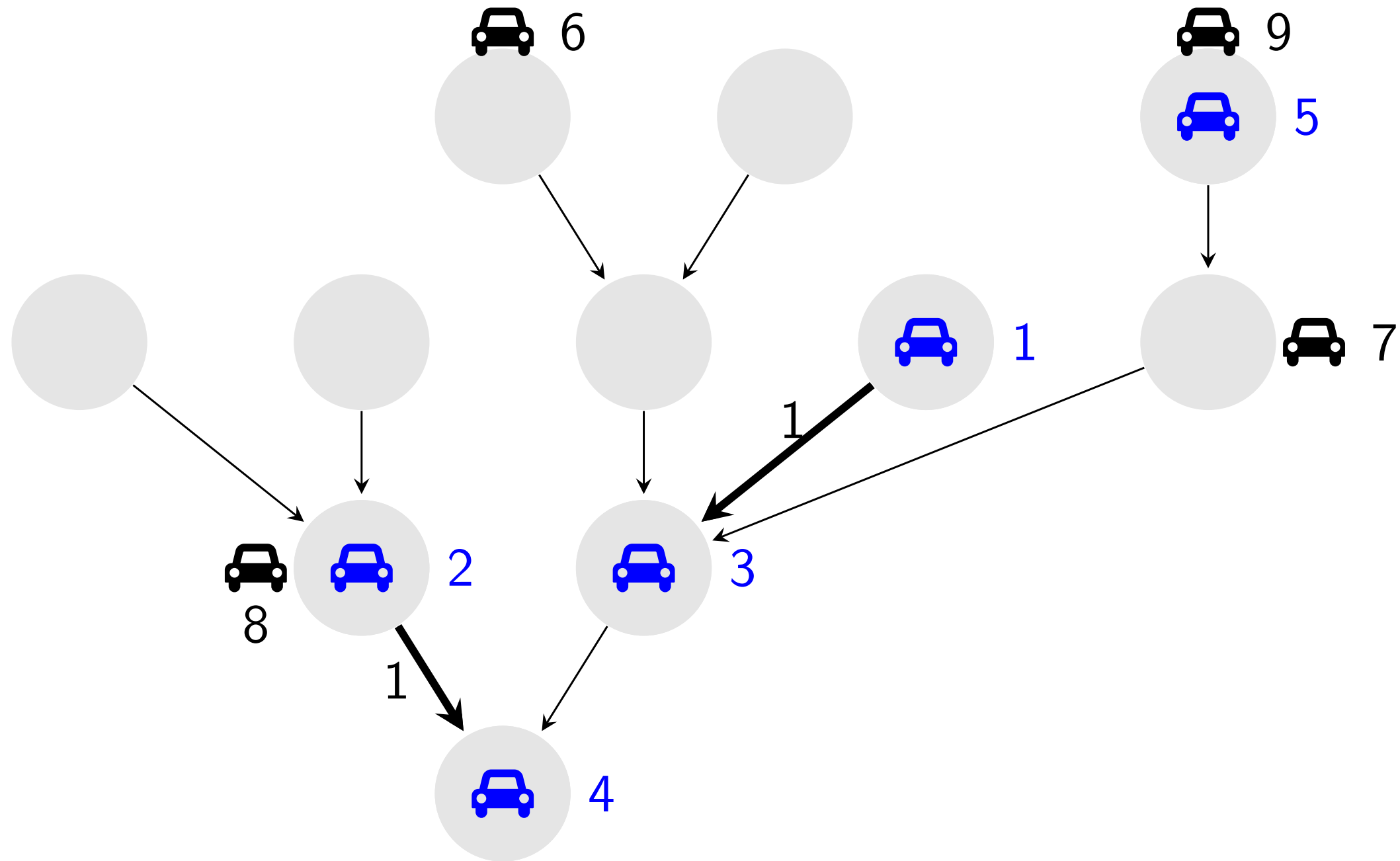


# Parking rules on a tree



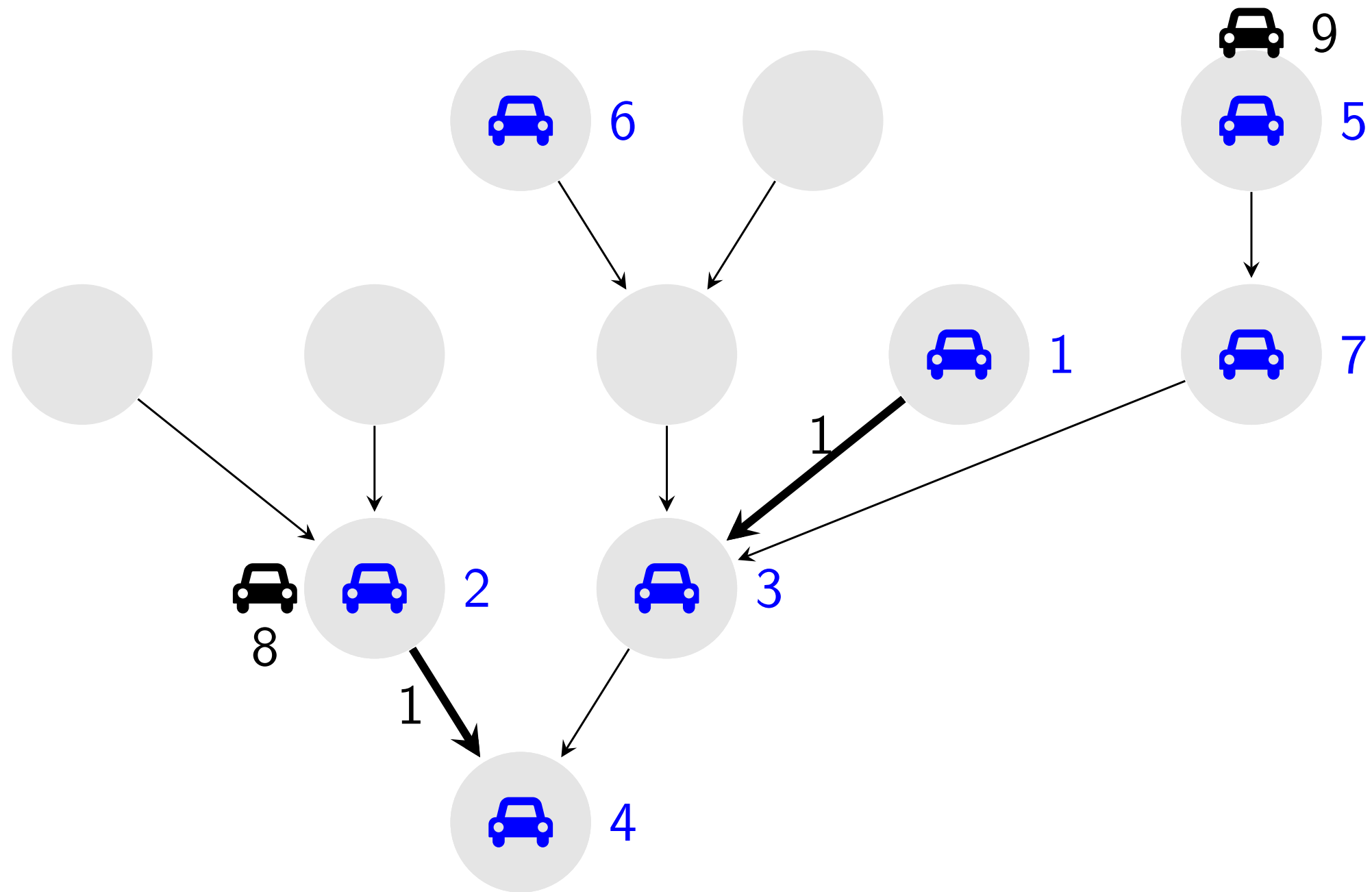


# Parking rules on a tree

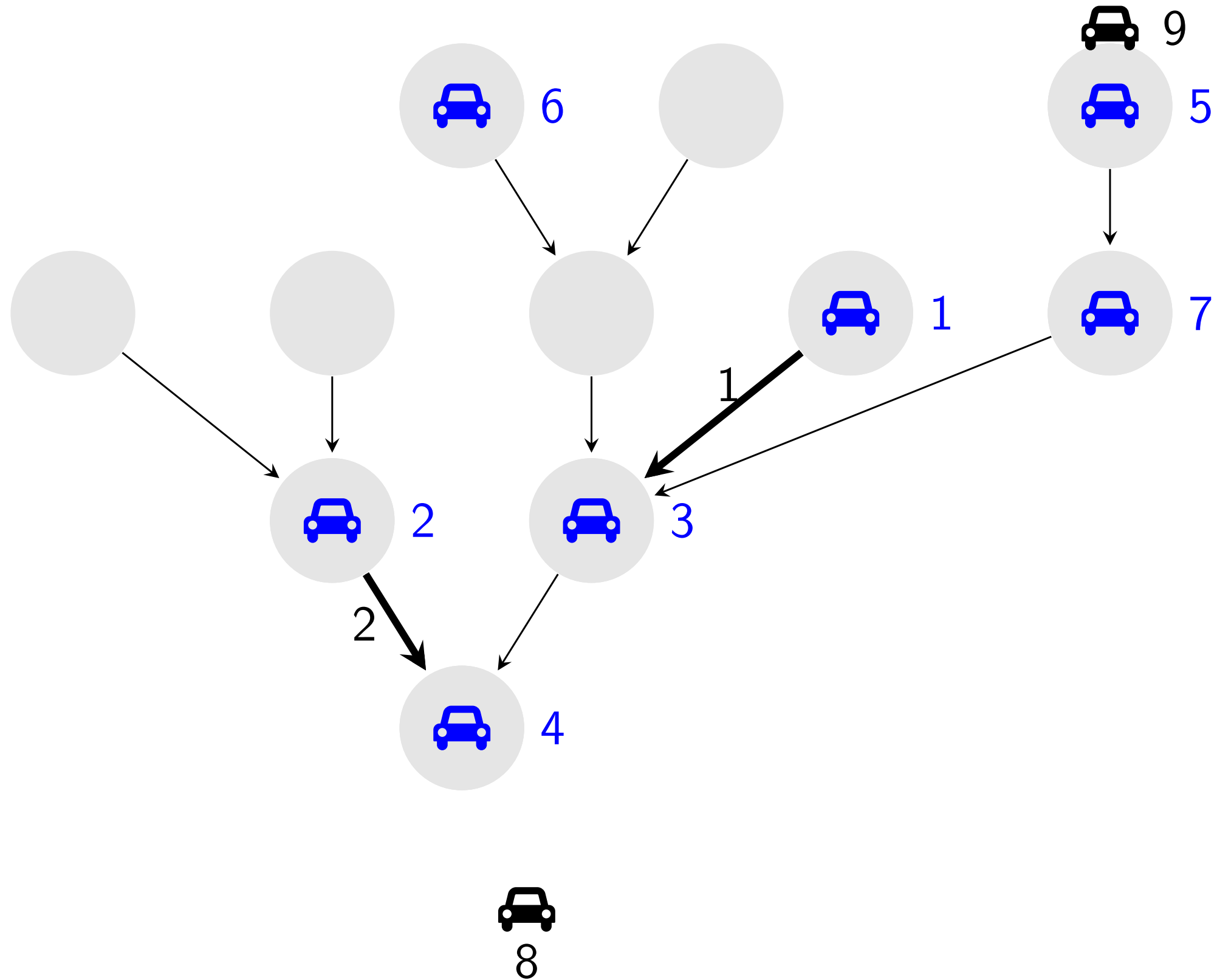




# Parking rules on a tree



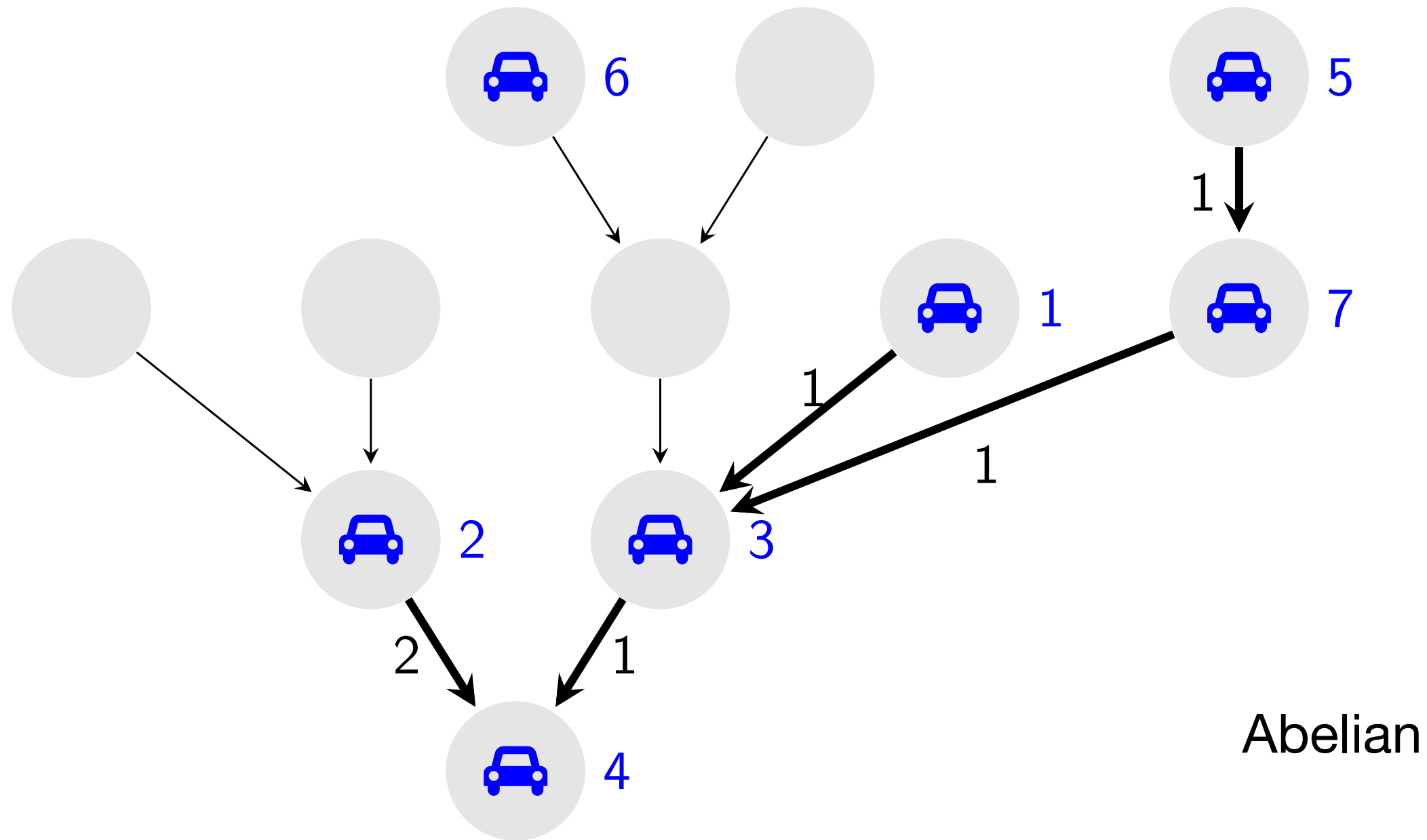
# Parking rules on a tree







# Parking rules on a tree



# Motivations

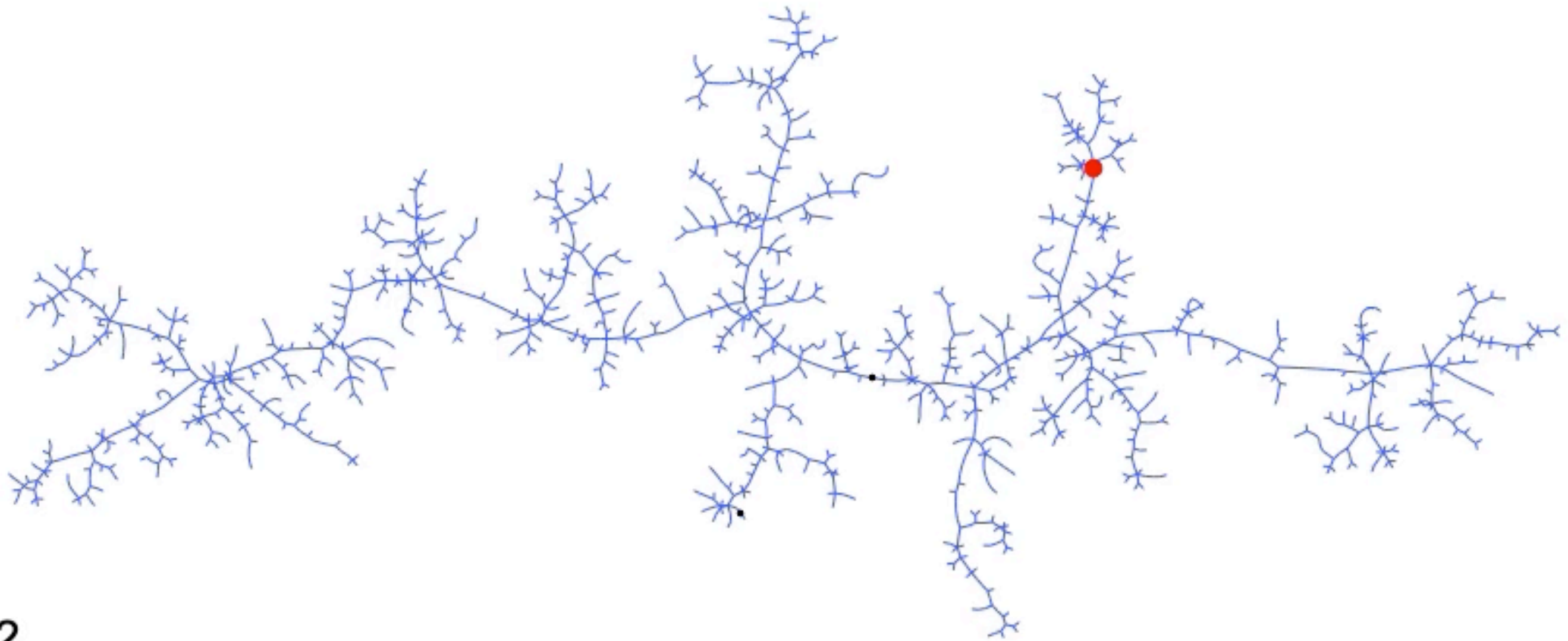


# Model

- We choose a (finite or infinite) tree  $\mathcal{T}$
- Conditionally on  $\mathcal{T}$ , the cars arrive one by one uniformly on the vertices.
- **Goal** : study the *flux* of outgoing cars, the size of the *components* of parked cars, their *geometry*...



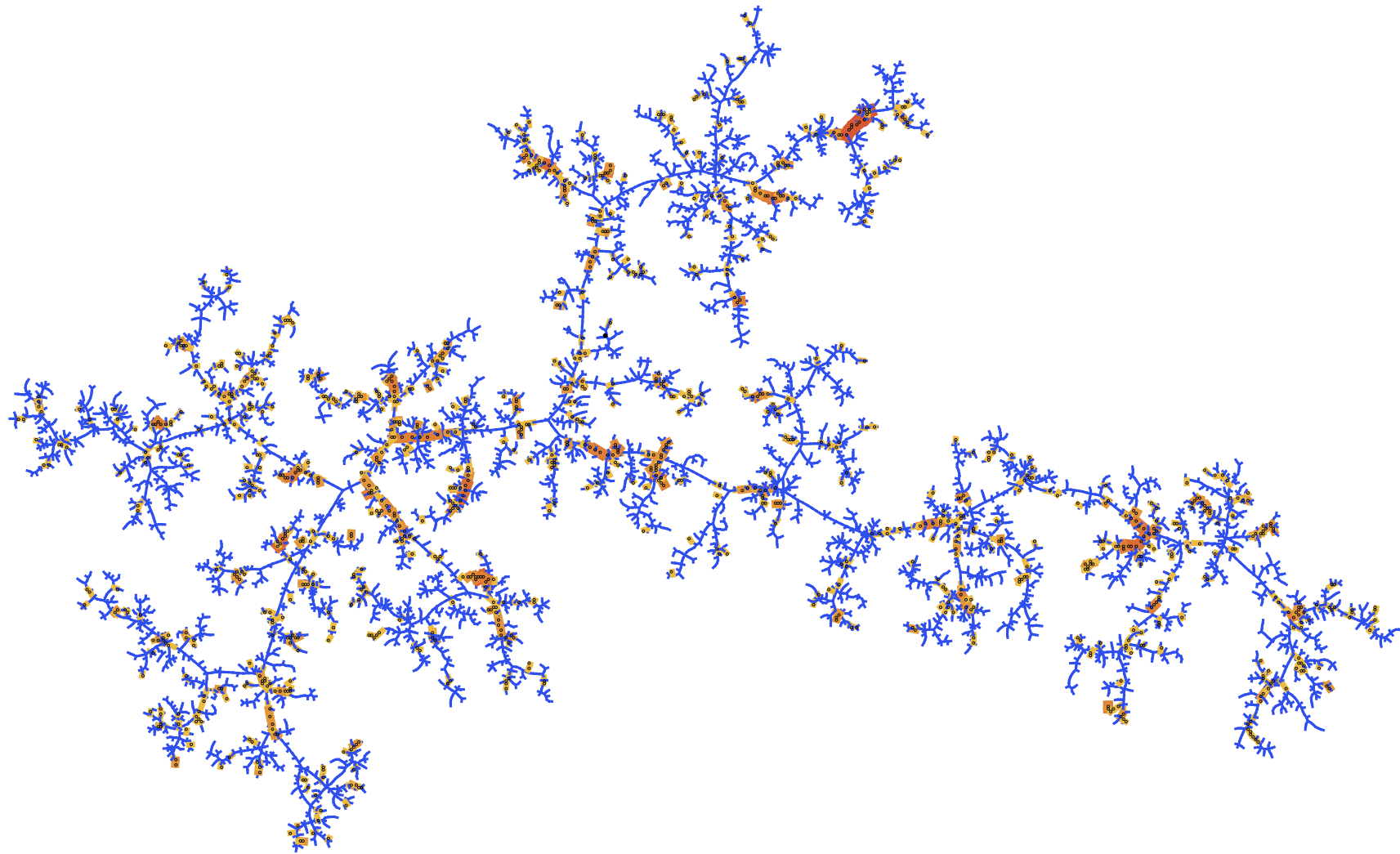
# Movie



2

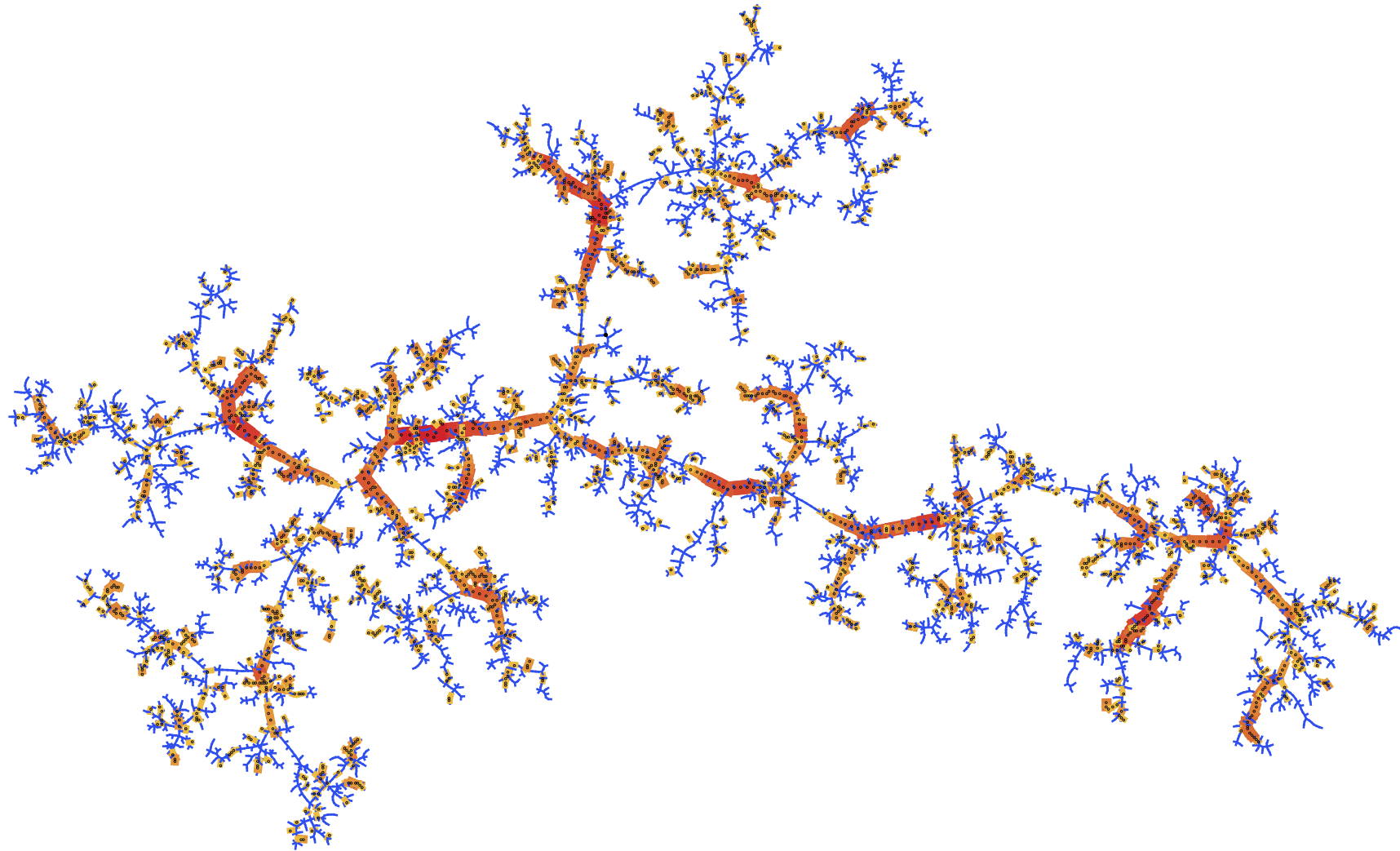
Phase transition

# Subcritical regime



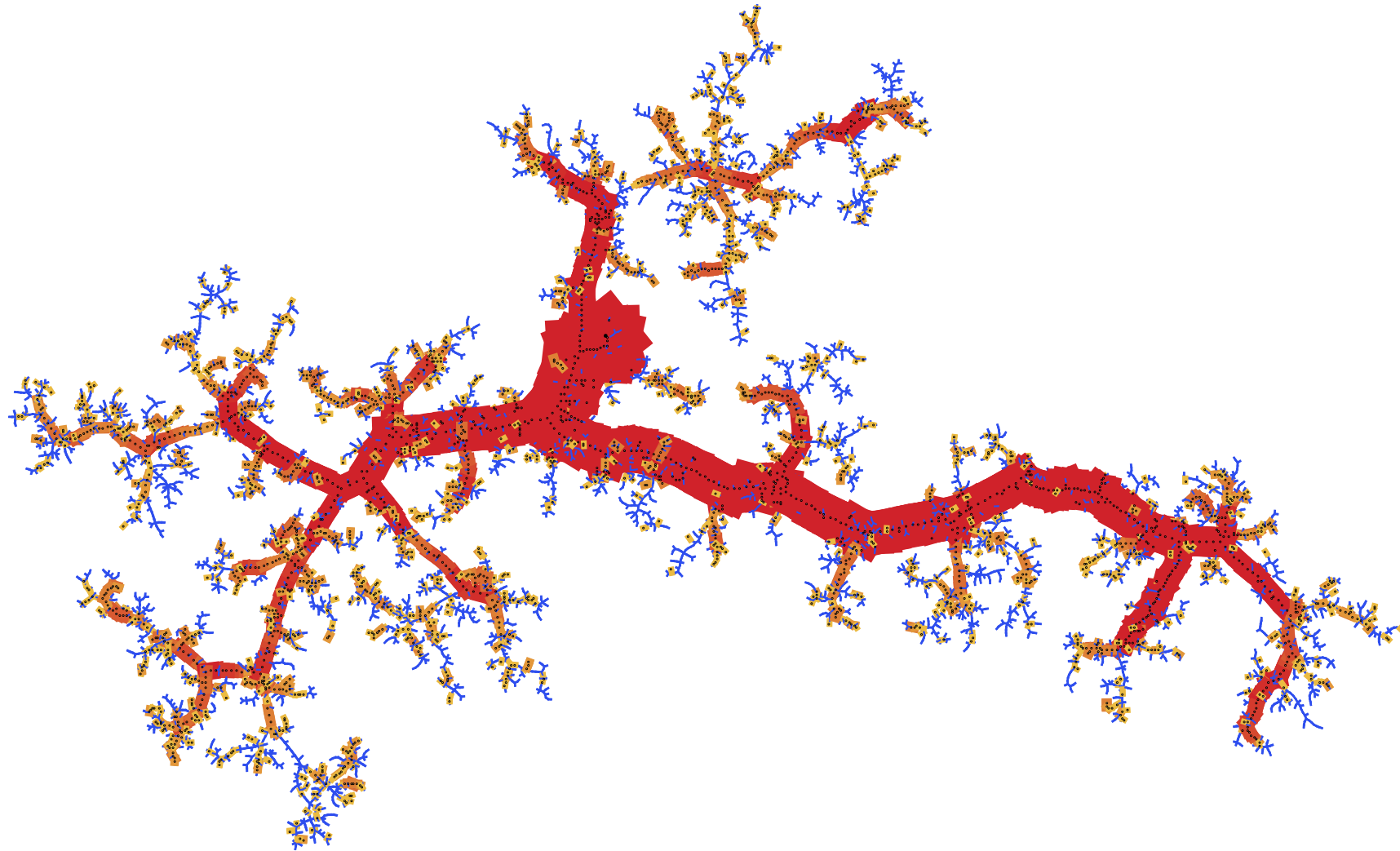
Flux of outgoing cars  $= o_{\mathbb{P}}(n)$

# Critical regime



Flux of outgoing cars  $= o_{\mathbb{P}}(n)$

# Supercritical regime



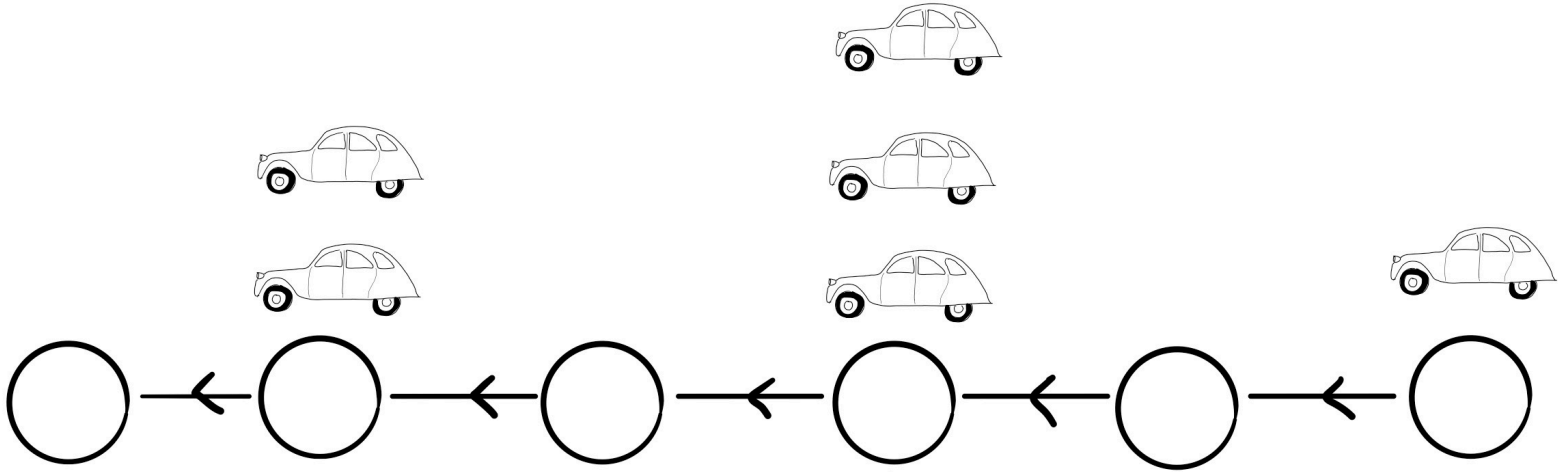
$$\text{Flux of outgoing cars} = (c + o_{\mathbb{P}}(1))n$$

# Phase transition

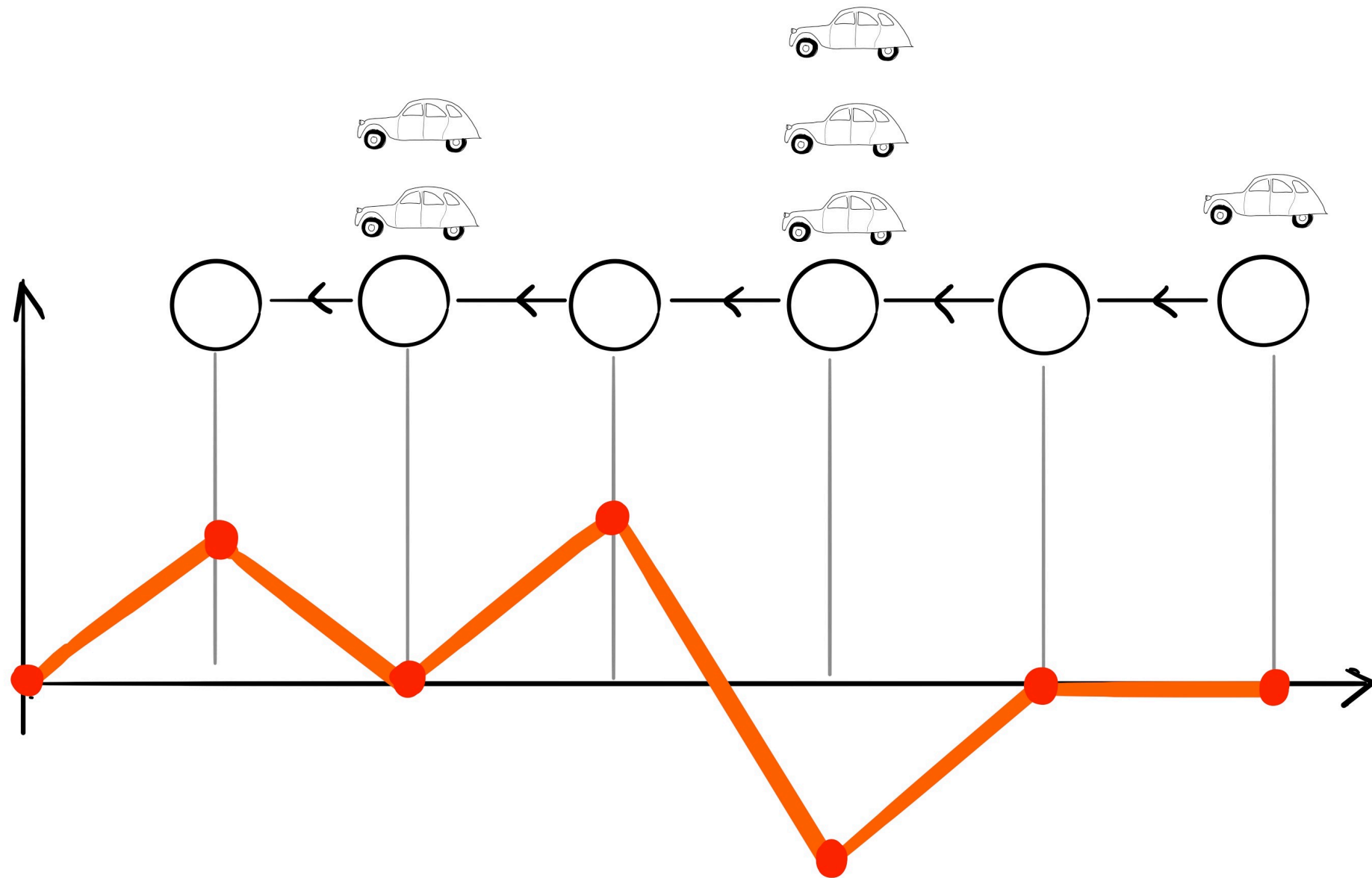
- In the subcritical regime, the flux is sublinear.
- In the supercritical regime, the flux is linear.
- We take a stochastically increasing family of probability measures  $(\mu^\alpha : \alpha \in \mathbb{R})$ .
- Critical parameter  $\alpha_c \longrightarrow$  phase transition
- Challenge : localize the phase transition and sharp understanding



# Case of the line



# Case of the line



"Trivial" phase transition

→  $\alpha = 1$  whatever the car arrival law

# History

- **1960** : Konheim & Weiss : [Line](#)
- **2015** : Lackner & Panholzer : [Uniform Cayley trees](#)
- **2016** : Jones : [Uniform binary trees](#)
- **2016** : Goldschmidt and Przykucki : [Uniform Cayley trees \(bis\)](#)
- **2019** : Chen and Goldschmidt : [Uniform plane trees](#)
- **2019** : Curien & Hénard (voir aussi C.): [Conditionned Bienaymé — Galton — Watson trees](#)
- **2021** : C. & Curien: [Uniform Cayley trees \(ter\)](#)
- **2022** : Aldous, C., Curien & Hénard: [Infinite binary tree](#)

...

# Three techniques for parking **on a tree**

**Local limit and  
differential equations**

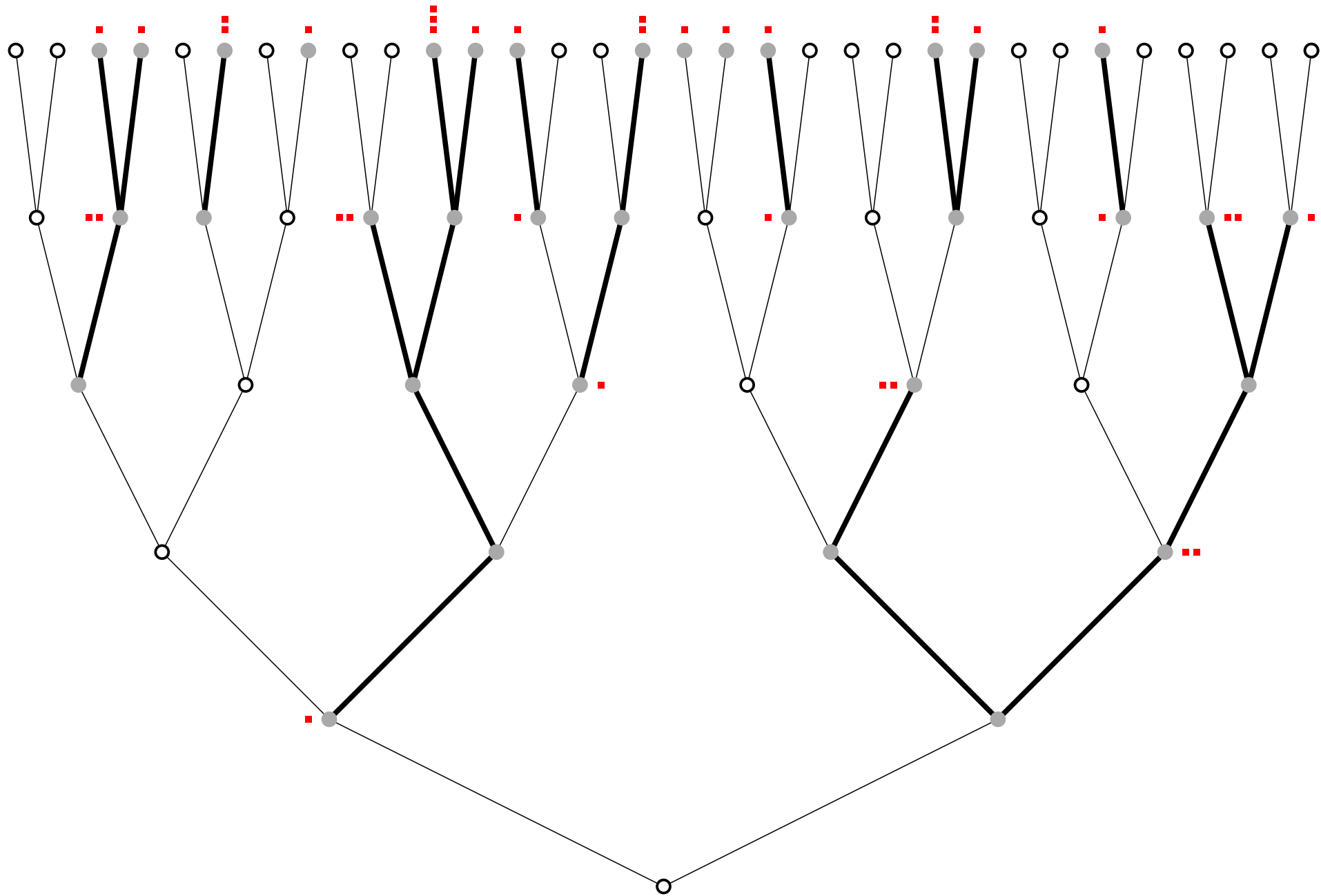
**Coupling with the  
Erdős—Rényi random graph**

**Combinatorial decomposition  
and "à la Tutte" recursion**

Infinite binary tree:

Combinatorial decomposition  
and "à la Tutte" recursion

# Infinite binary tree



- I.i.d. car arrivals with law  $\mu$ . We denote by  $G$  its generating function

$$G(t) = \sum_{k \geq 0} \mu_k t^k$$

# Localisation of the phase transition

## Theorem (Aldous, C., Curien & Hénard, 2022) :

Suppose that there exists

$$t_c = \min\{t \geq 0, 2(G(t) - tG'(t))^2 = t^2G(t)G''(t)\}.$$

The parking process is subcritical if and only if

$$(t_c - 2)G(t_c) \geq t_c(t_c - 1)G'(t_c).$$

In general, the parameter  $t_c$  exists.

# Examples

Car arrivals	Critical value $\alpha_c$
<b>Binary 0/2</b> $\mu^\alpha = (1 - \frac{\alpha}{2})\delta_0 + \frac{\alpha}{2}\delta_2$	$\frac{1}{14}$
<b>Poisson</b> $G_\alpha(t) = \exp(t(a - 1))$	$3 - 2\sqrt{2}$
<b>Geometric</b> $G_\alpha(t) = \frac{1}{1 + \alpha - \alpha t}$	$\frac{1}{8}$

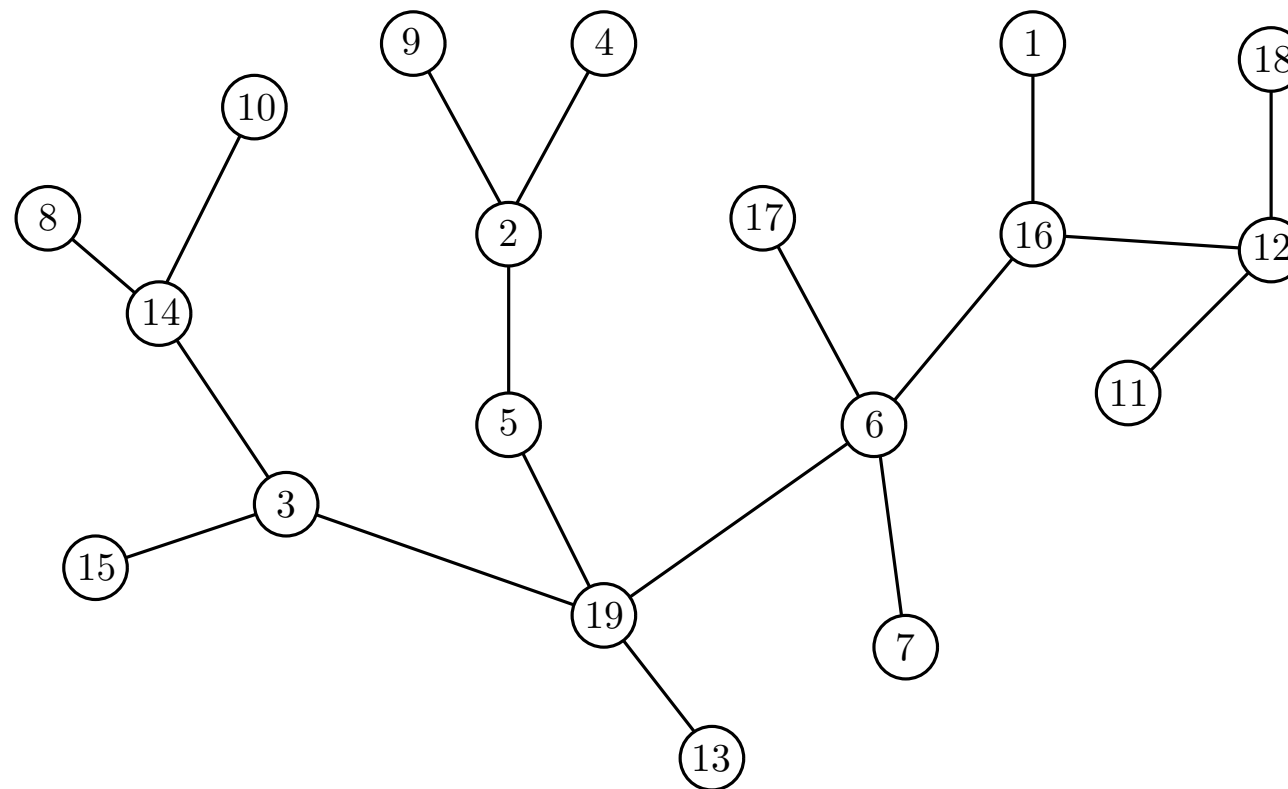


Cayley trees :

Coupling  
with the Erdős—Rényi random graph

# Model

- We take a uniform Cayley tree  $\mathcal{T}_n$  with  $n$  vertices.



- $m = \alpha n$  cars arrive sequentially, uniformly and independently on the vertices of  $\mathcal{T}_n$ .

## Theorem (C. & Curien, 2021):

We can couple the parking process and the Erdős–Rényi random graph model.

The phase transition occurs at  $\alpha_c = 1/2$ .

In the critical window, that is when

$$m = \left\lfloor \frac{n}{2} + \frac{\lambda}{2} \cdot n^{2/3} \right\rfloor, \text{ with } \lambda \in \mathbb{R},$$

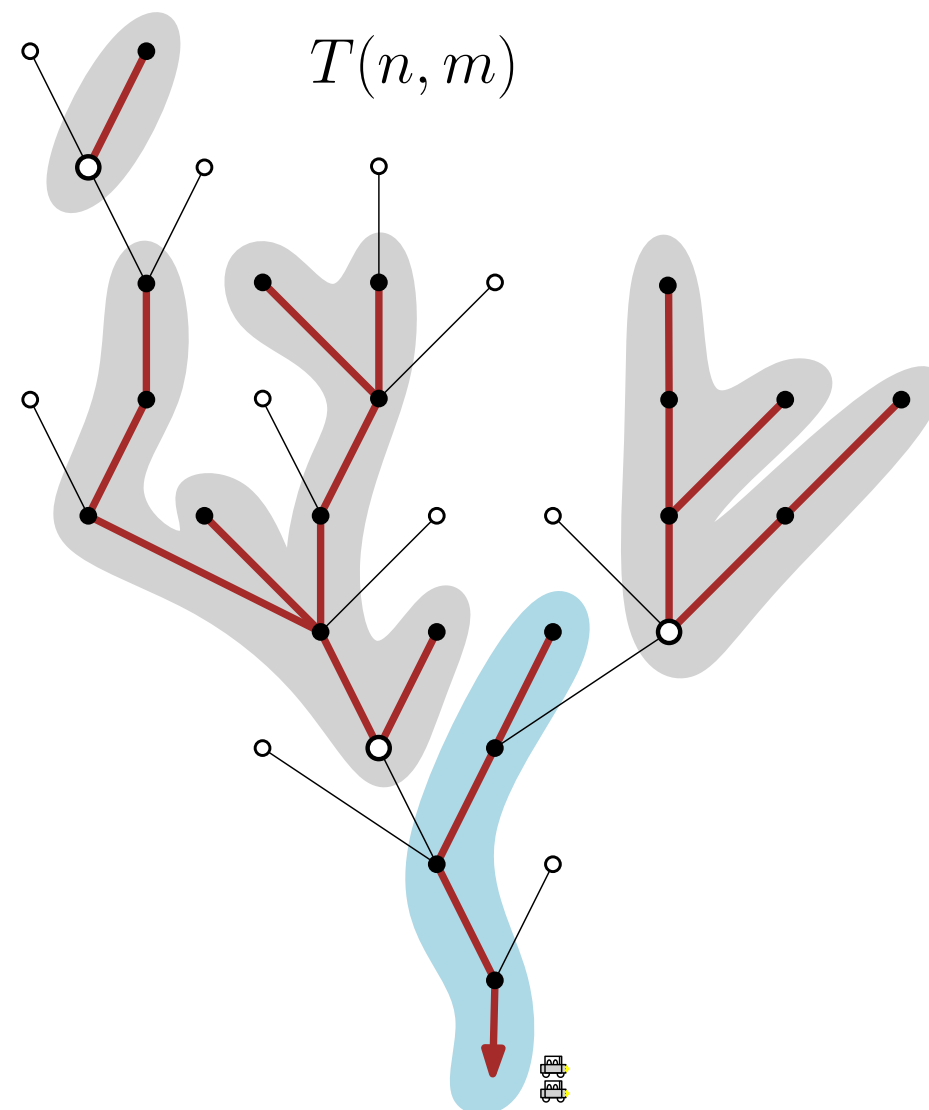
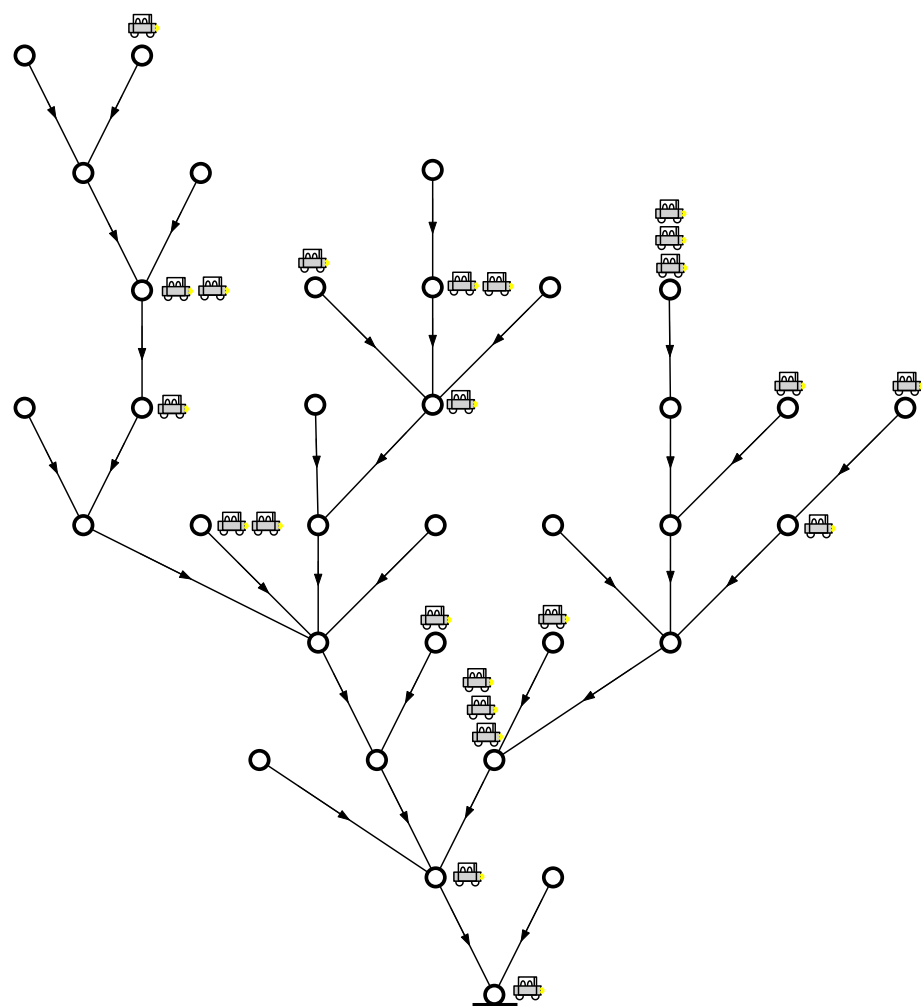
the clusters of parked cars have size of order  $n^{2/3}$ , and the flux of outgoing cars is of order  $n^{1/3}$ .

# Markovian exploration



**Idea :** Consider the underlying tree as unknown and discover its edges step-by-step while parking the cars.

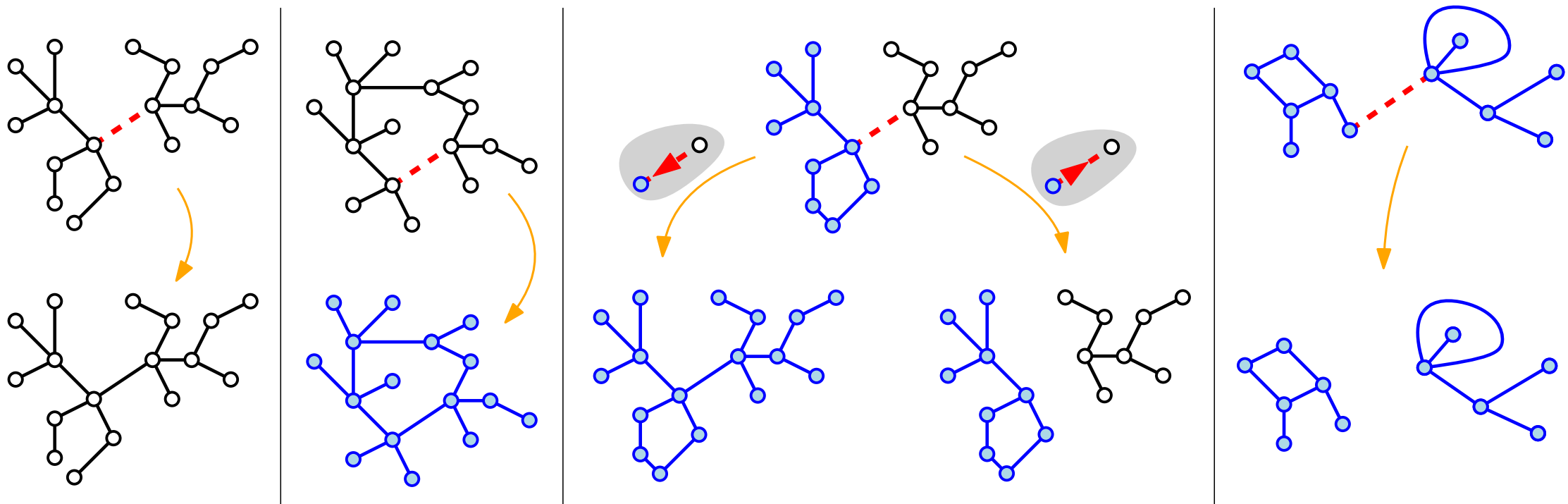
$T(n, m)$  forest containing the edges emanating from the occupied spots.



$T(n, m)$  is a Markov chain.

# The frozen Erdős—Rényi random graph

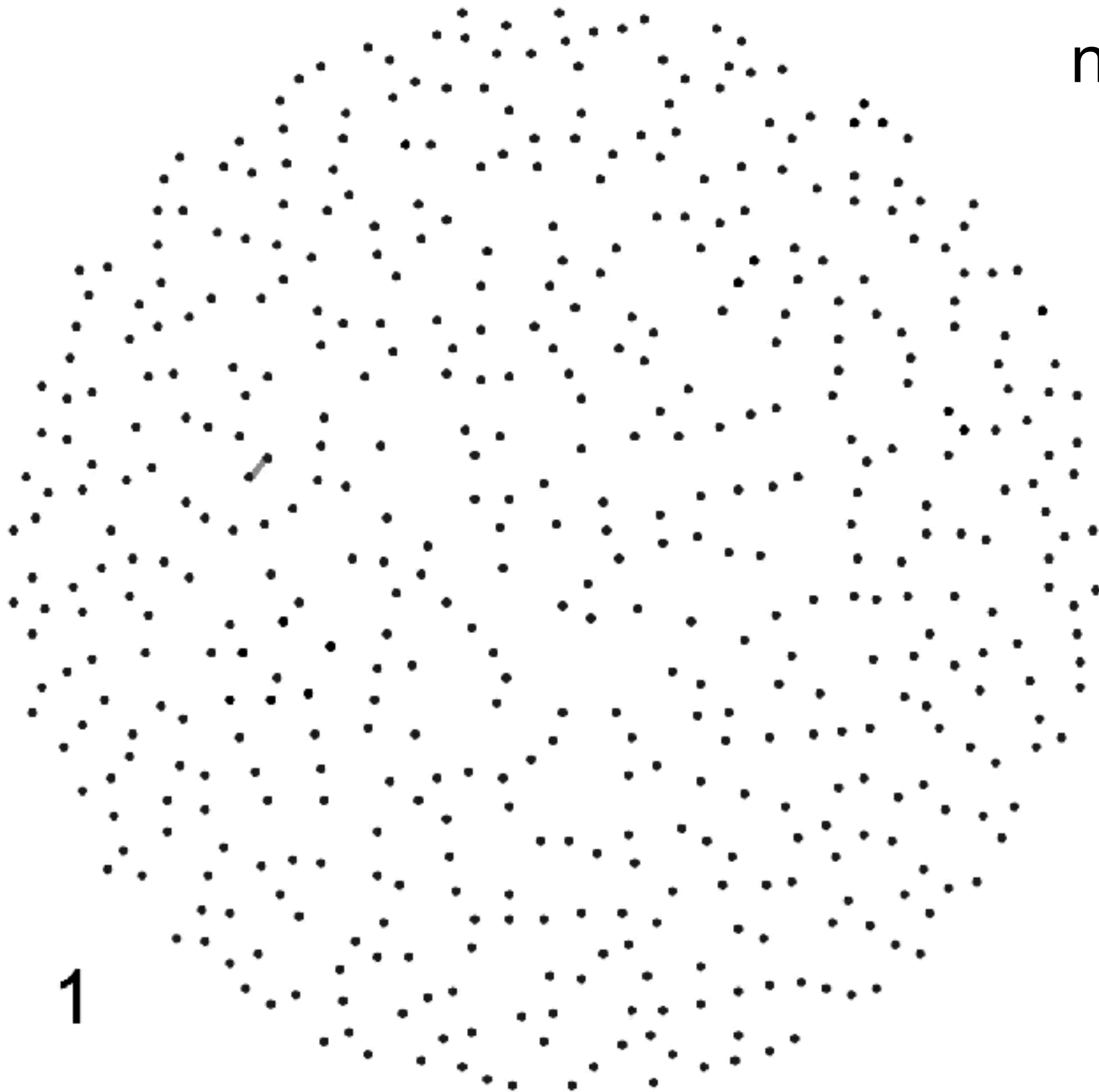
- Labeled vertices  $\{1, 2, \dots, n\}$ .
- For  $i \geq 1$ , oriented edge  $\vec{E}_i = (X_i, Y_i)$  where  $X_i$  and  $Y_i$  are two uniform vertices in  $\{1, 2, \dots, n\}$  and  $E_i$  its unoriented version.
- The **standard** Erdős—Rényi process  $G(n, m)$  with edges  $\{\{E_i : 1 \leq i \leq m\}\}$
- The **frozen** Erdős—Rényi process  $F(n, m)$ , white or blue vertices. We start with the forest of  $n$  white isolated vertices  $F(n, 0)$ . Then,



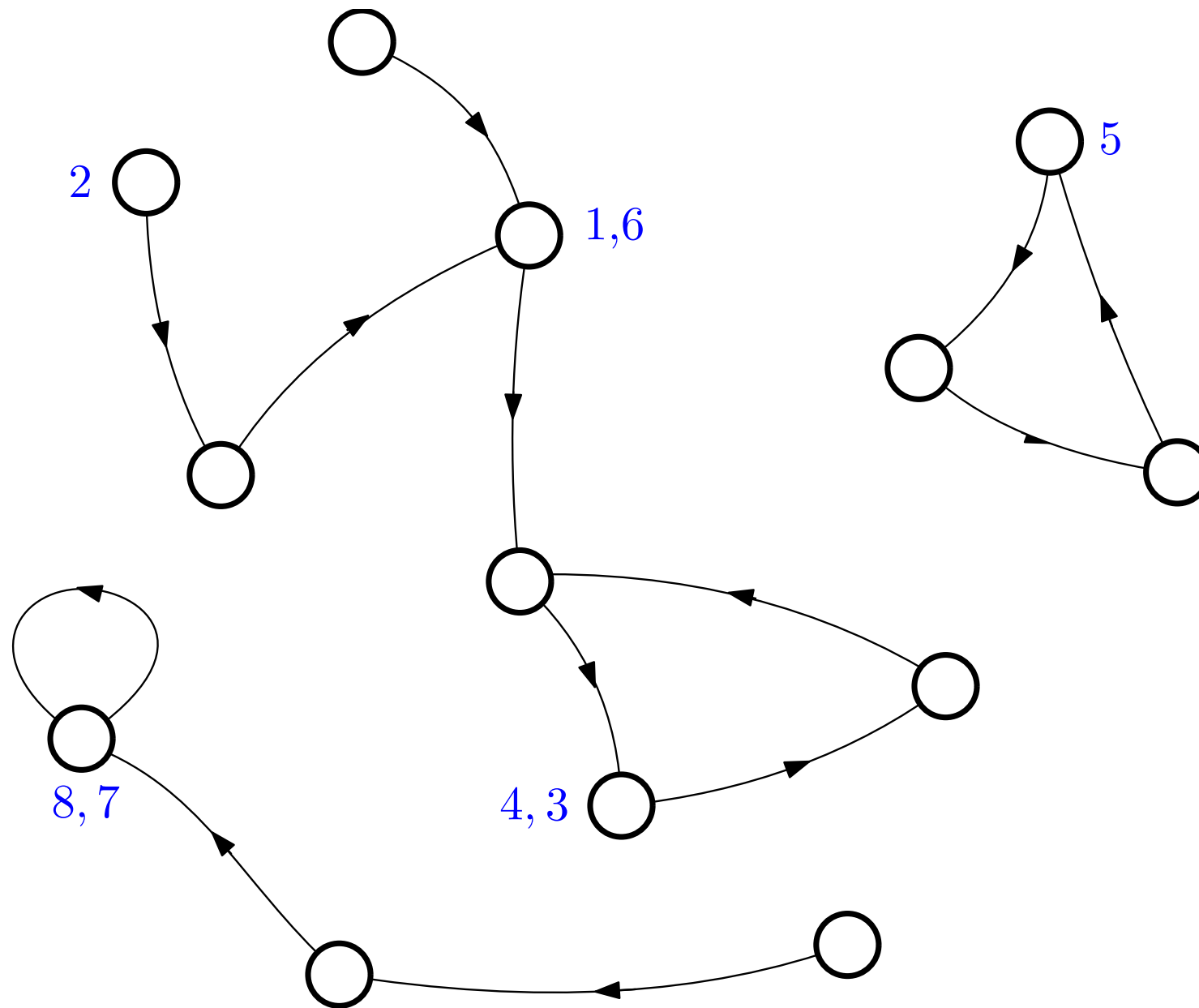
# Movie : the frozen Erdős—Rényi random graph

$n = 500$

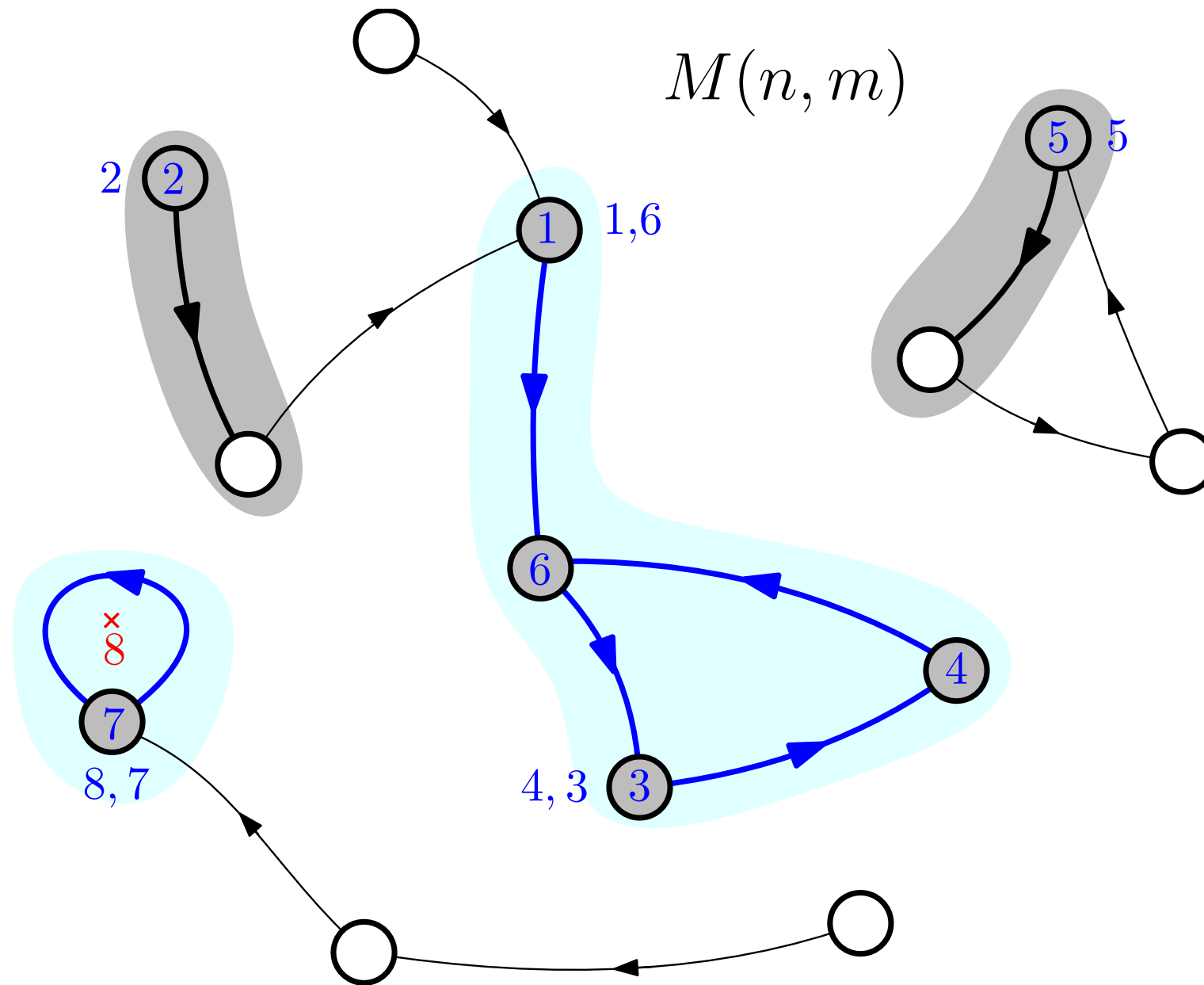
$m = 1$



# Parking on a mapping



# Parking on a mapping



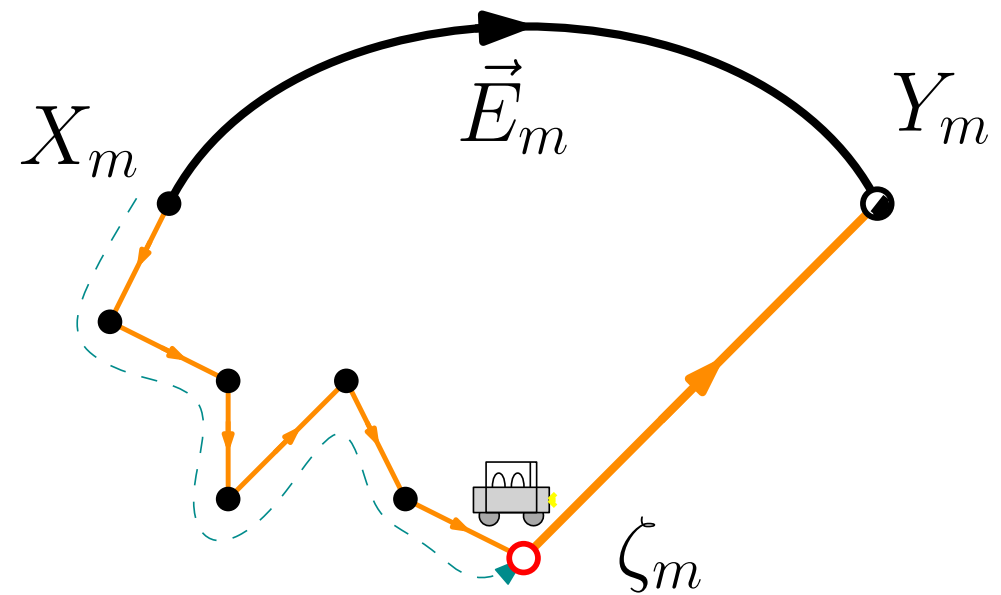
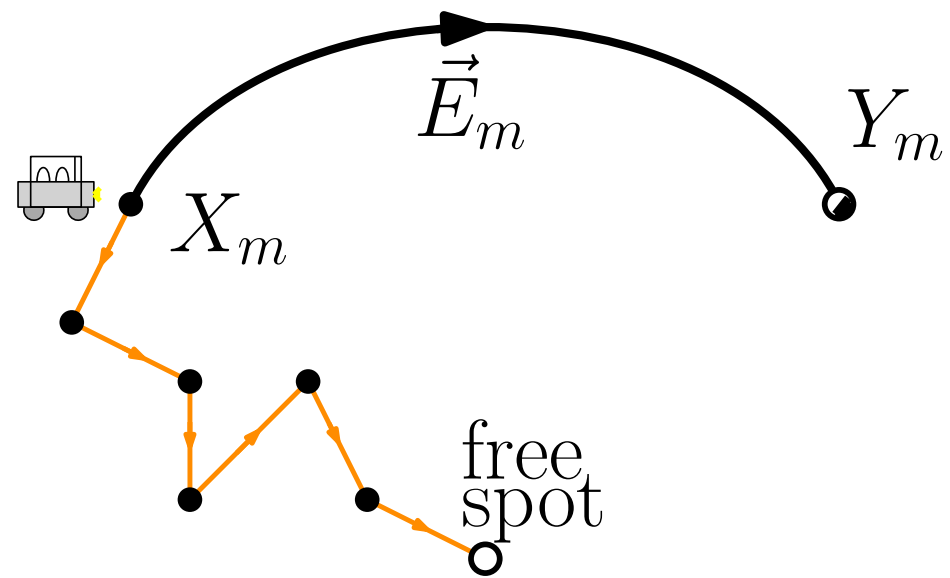


# Coupling parking and frozen ER

- We simultaneously built

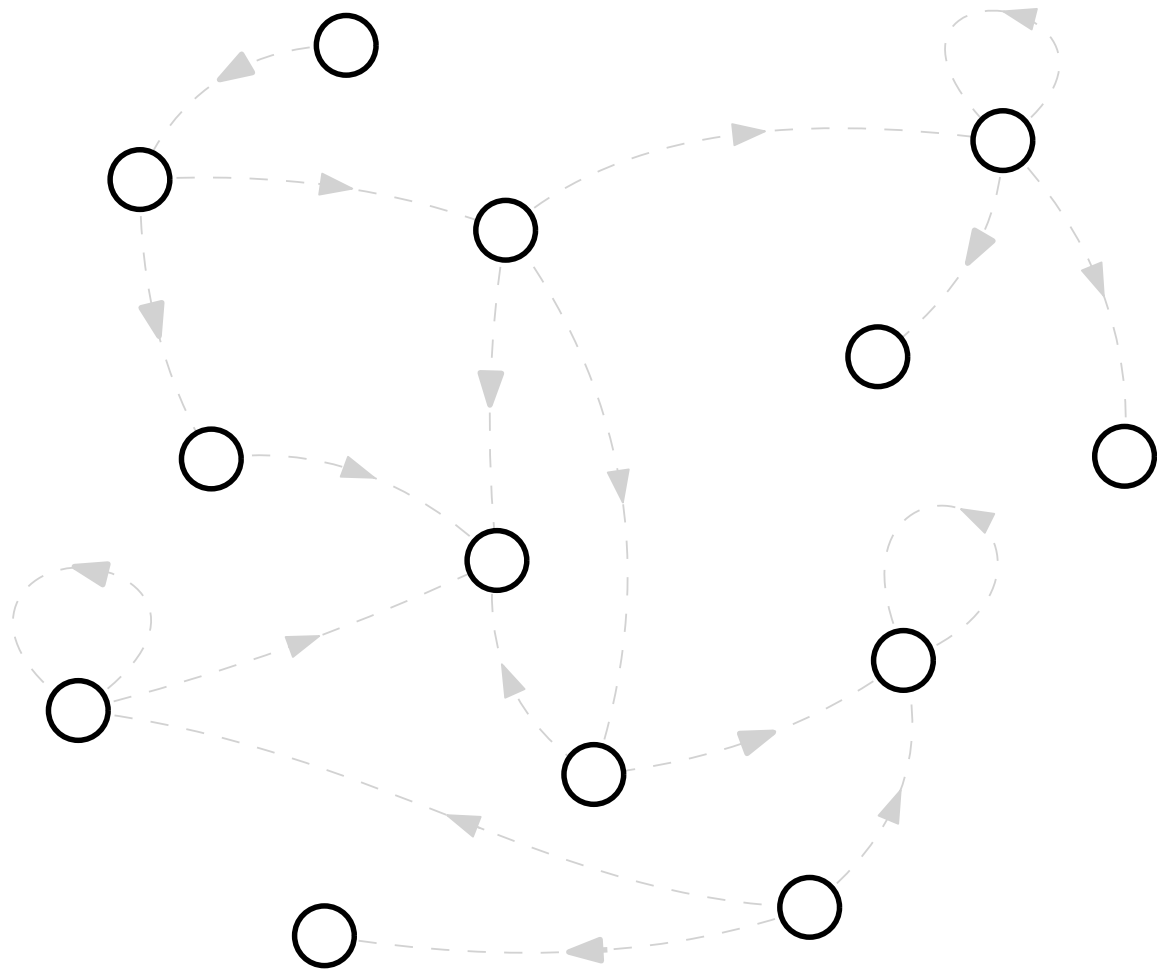
$$(F(n, m) : m \geq 0) \quad \text{and} \quad (M(n, m) : m \geq 0)$$

- Rule :

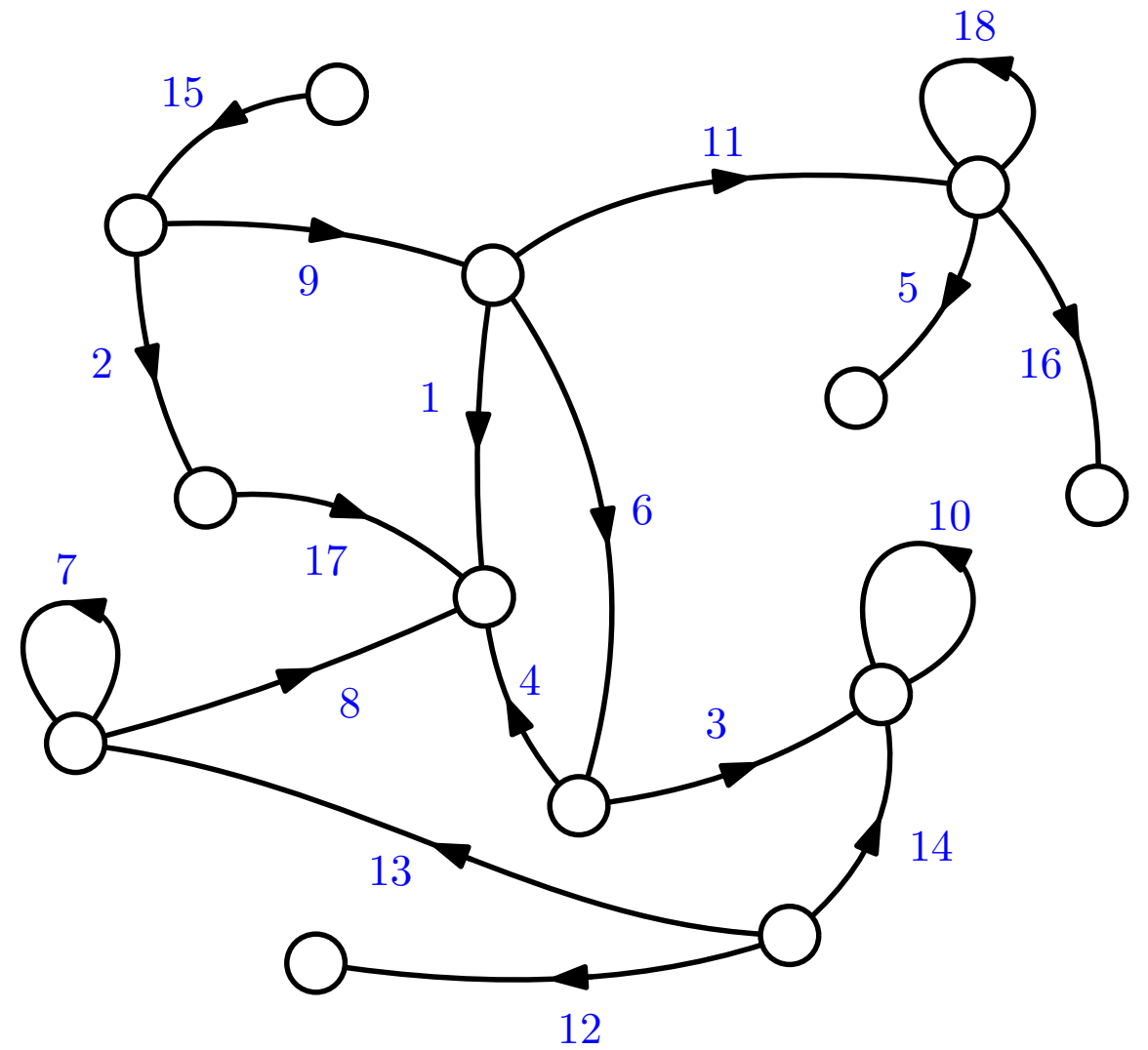


# Coupling

Parking on a mapping

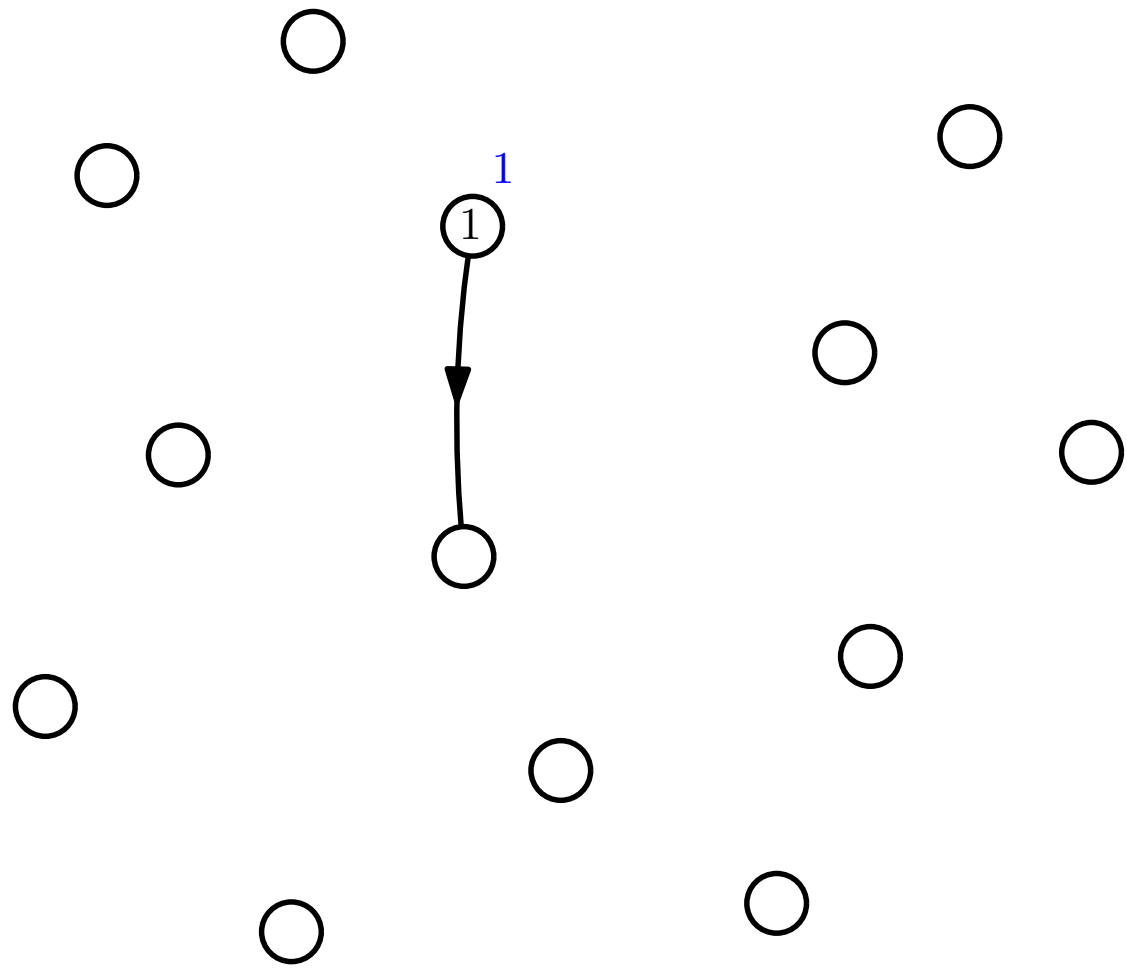


Erdős—Rényi

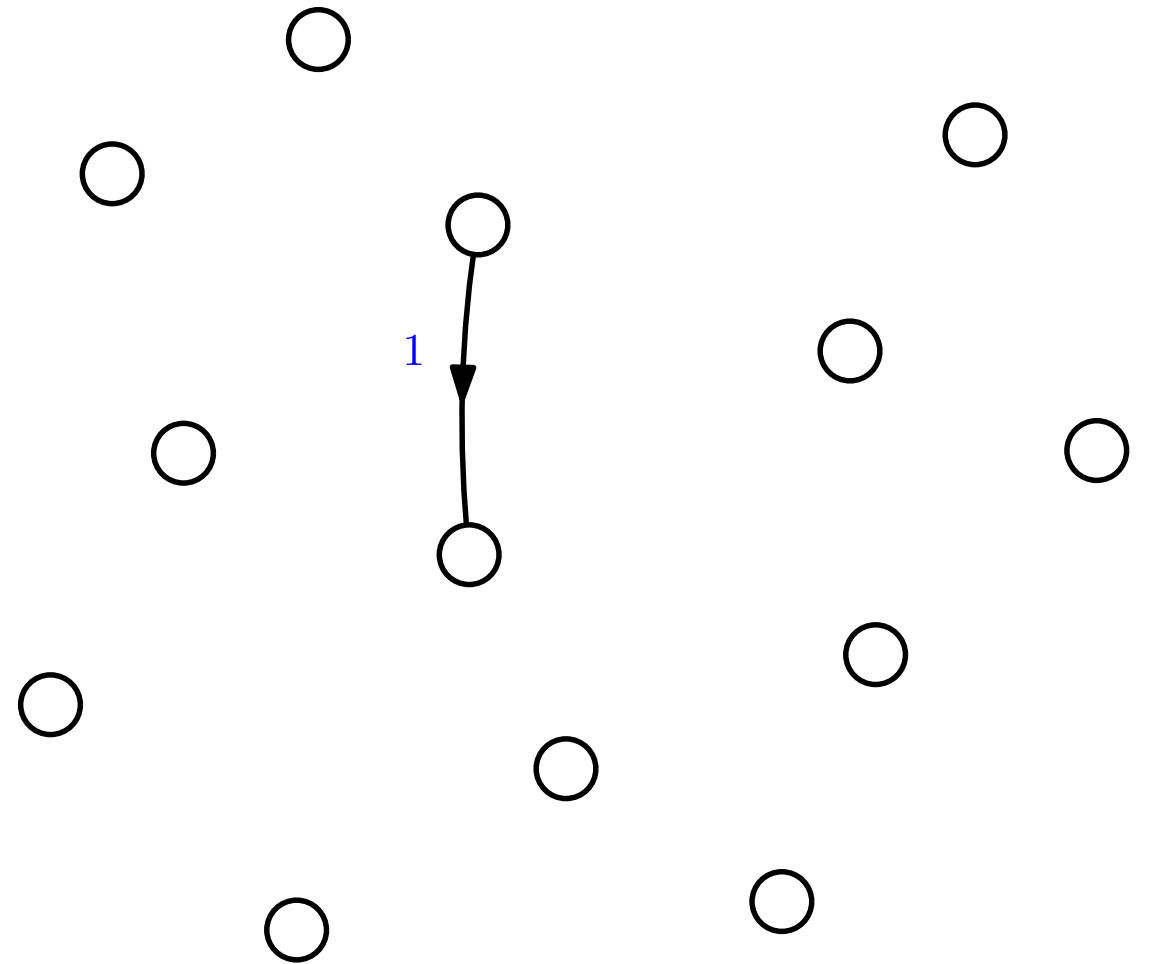


# Coupling

Parking on a mapping

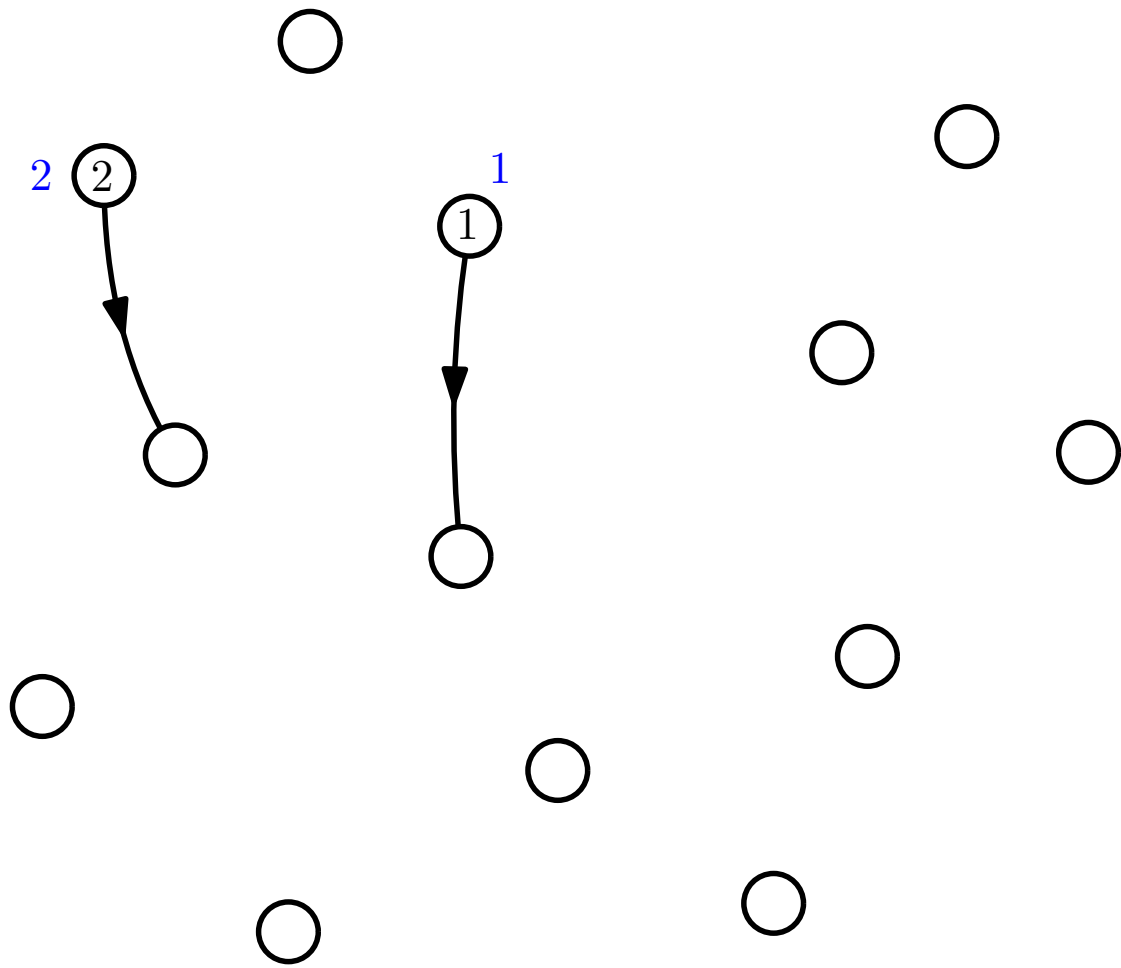


Frozen Erdős—Rényi

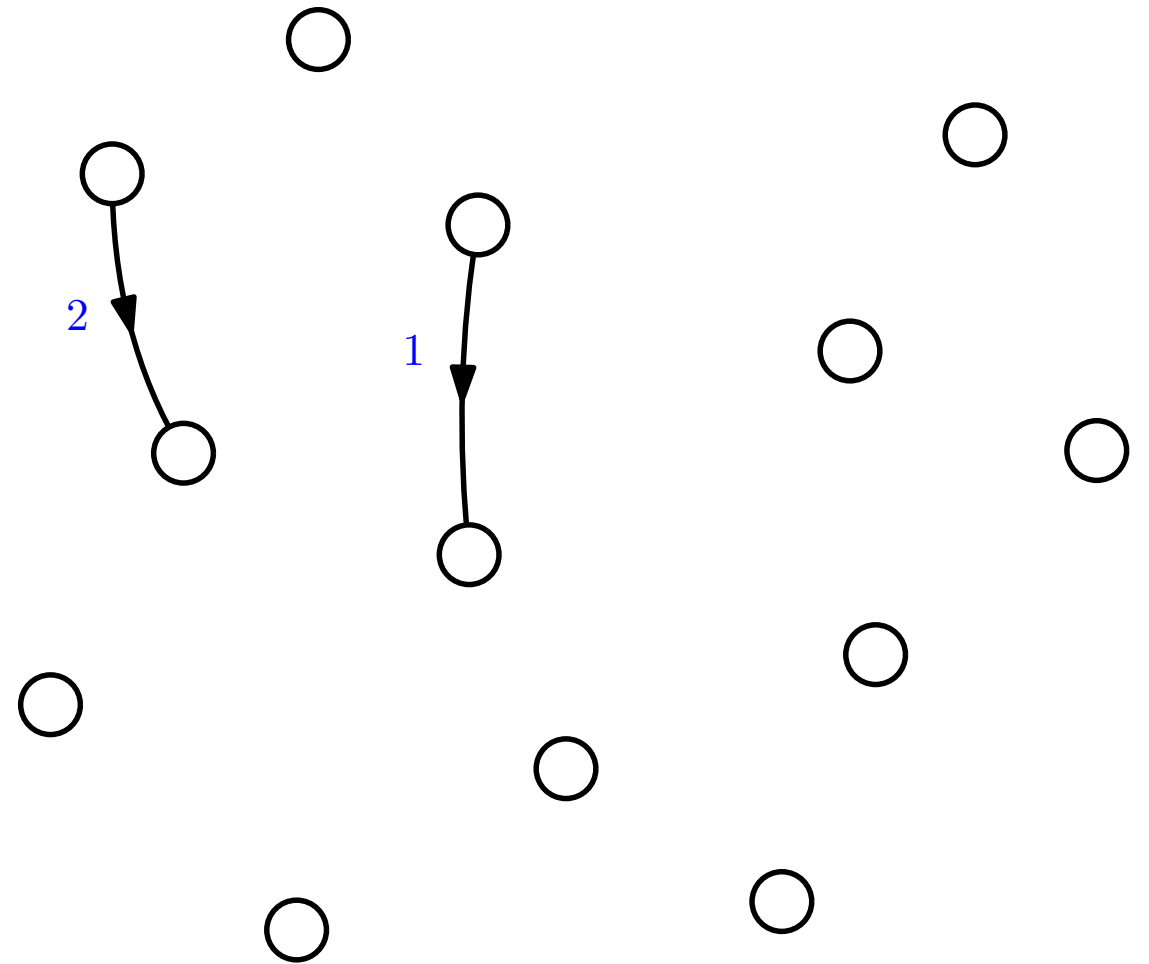


# Coupling

Parking on a mapping

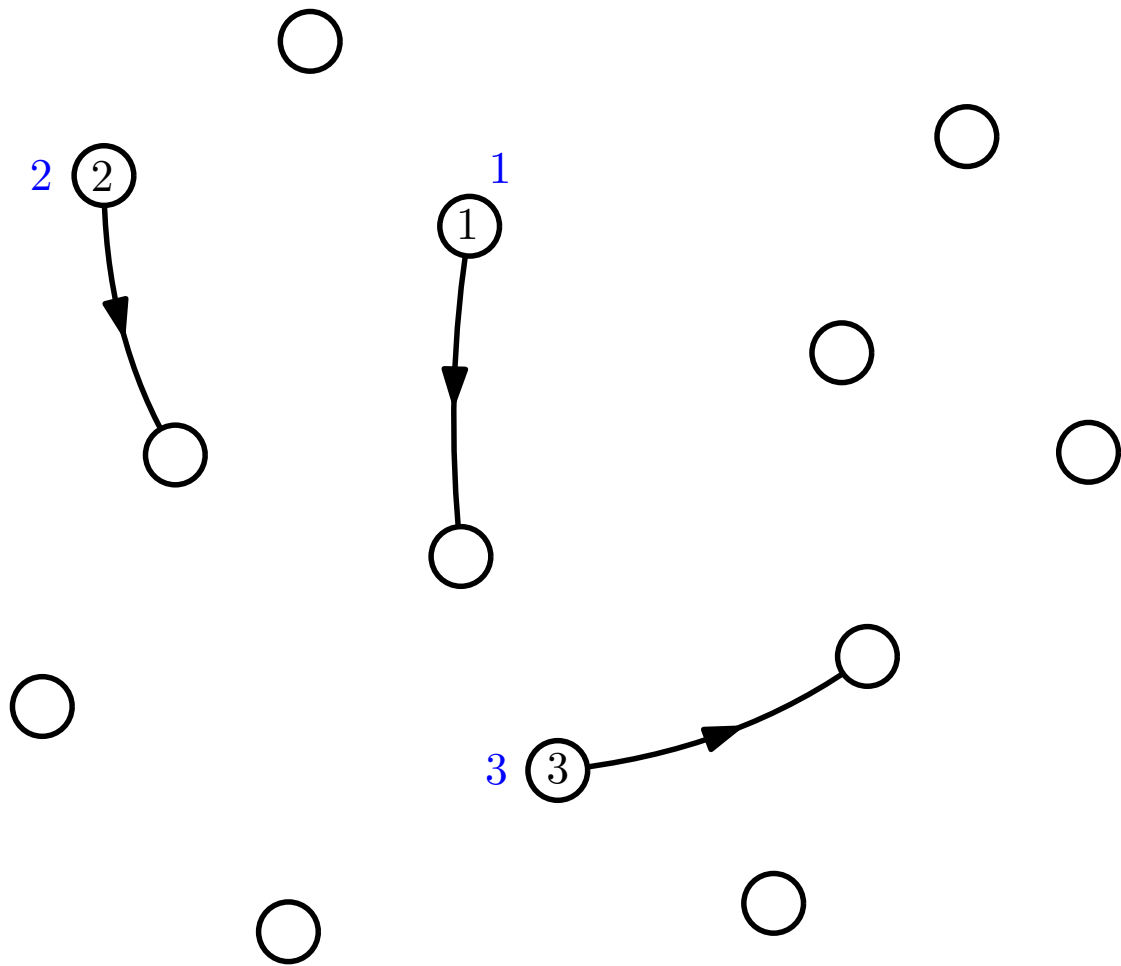


Frozen Erdős—Rényi

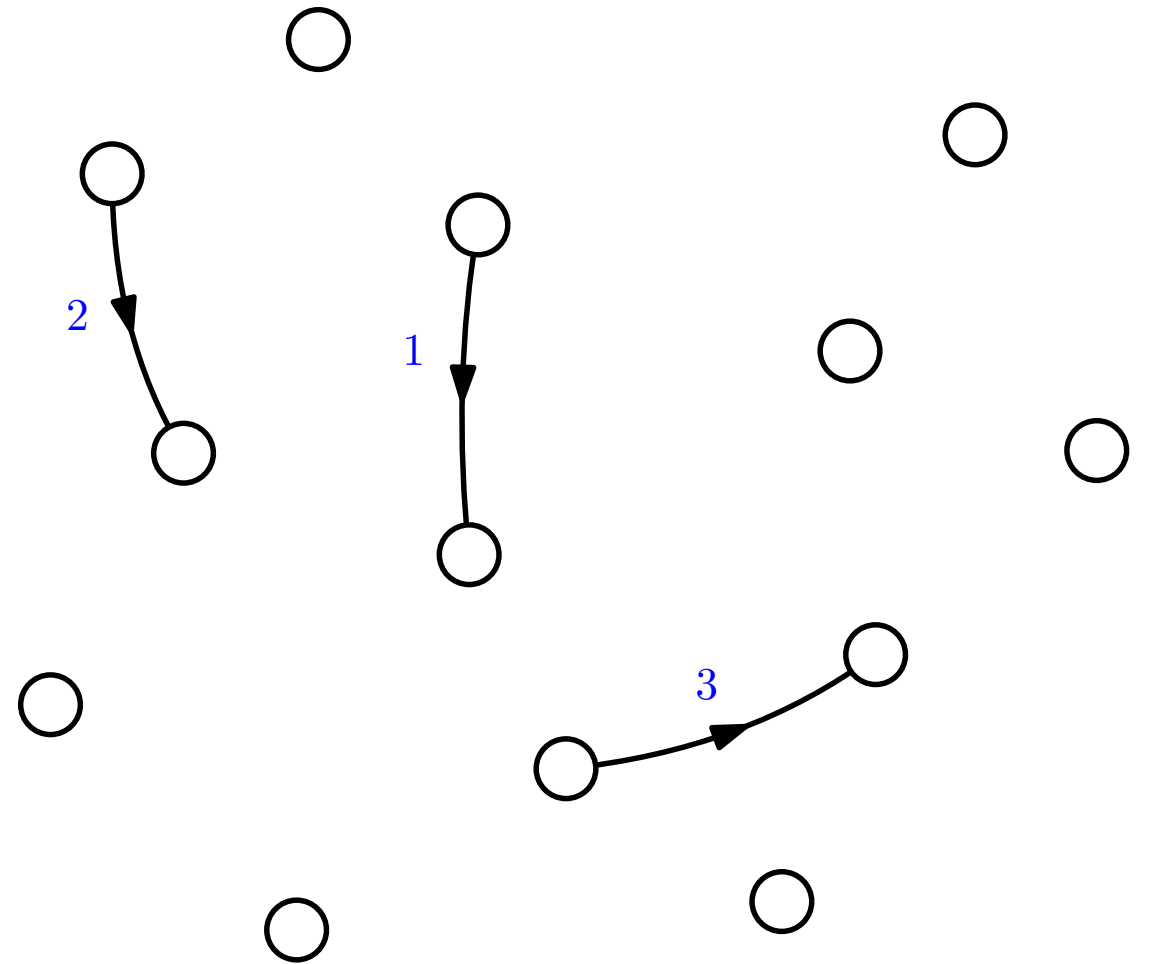


# Coupling

Parking on a mapping

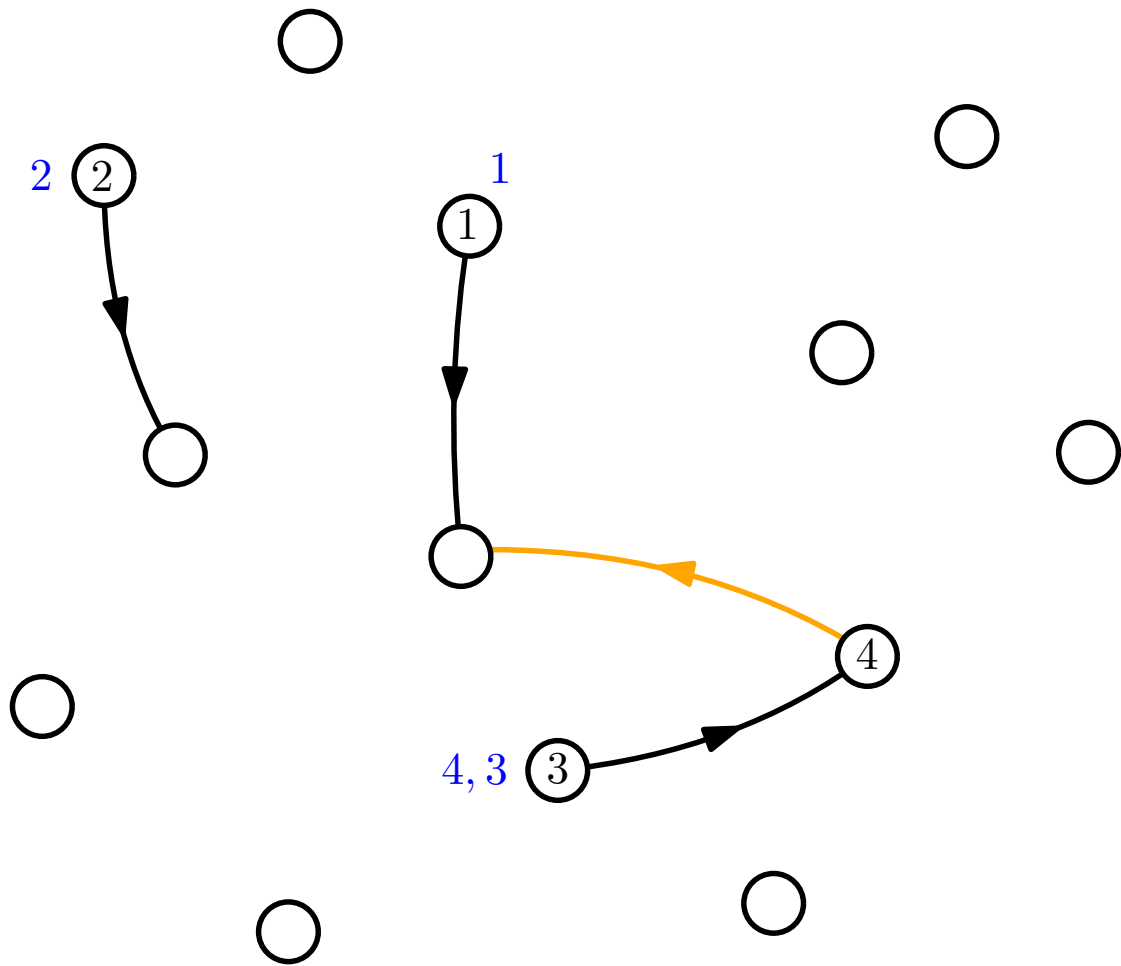


Frozen Erdős—Rényi

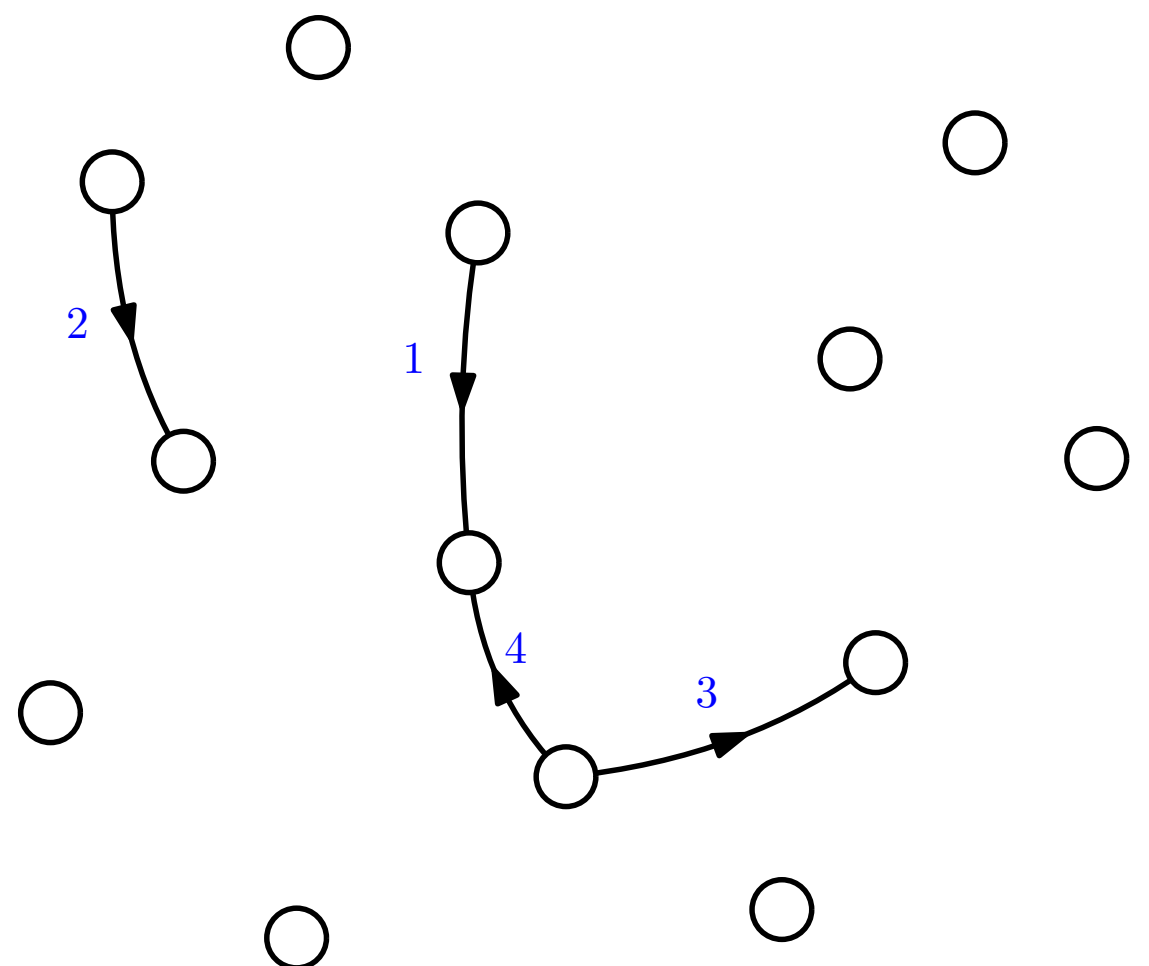


# Coupling

Parking on a mapping

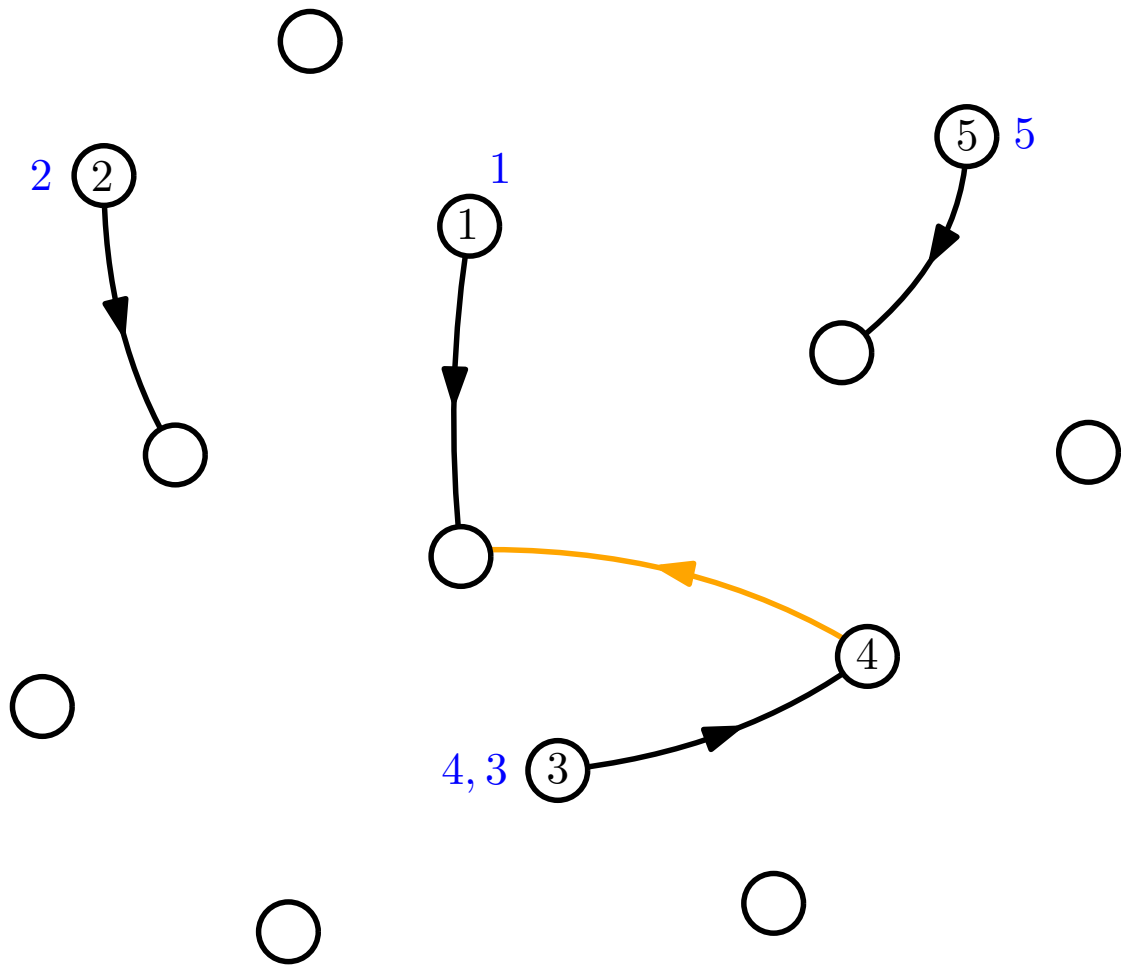


Frozen Erdős—Rényi

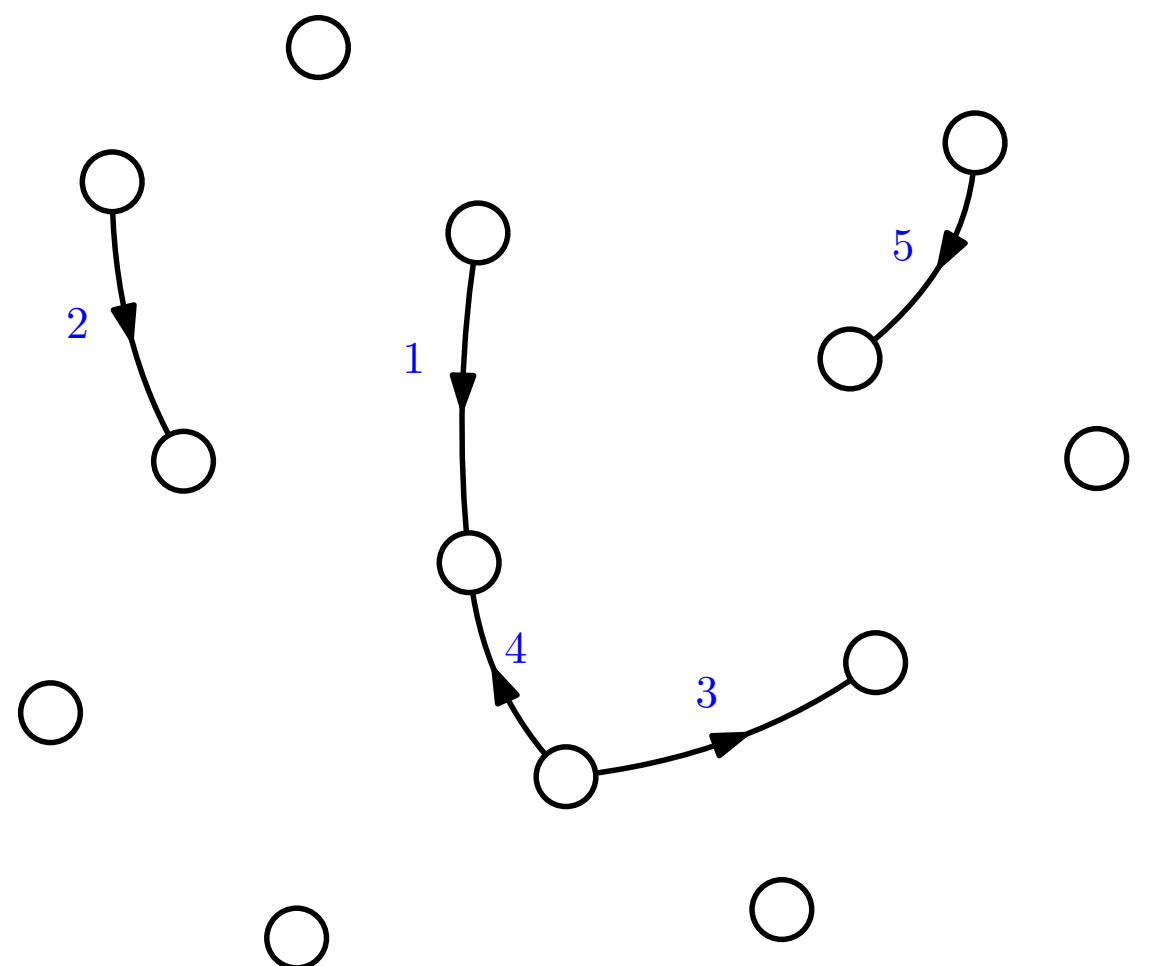


# Coupling

Parking on a mapping

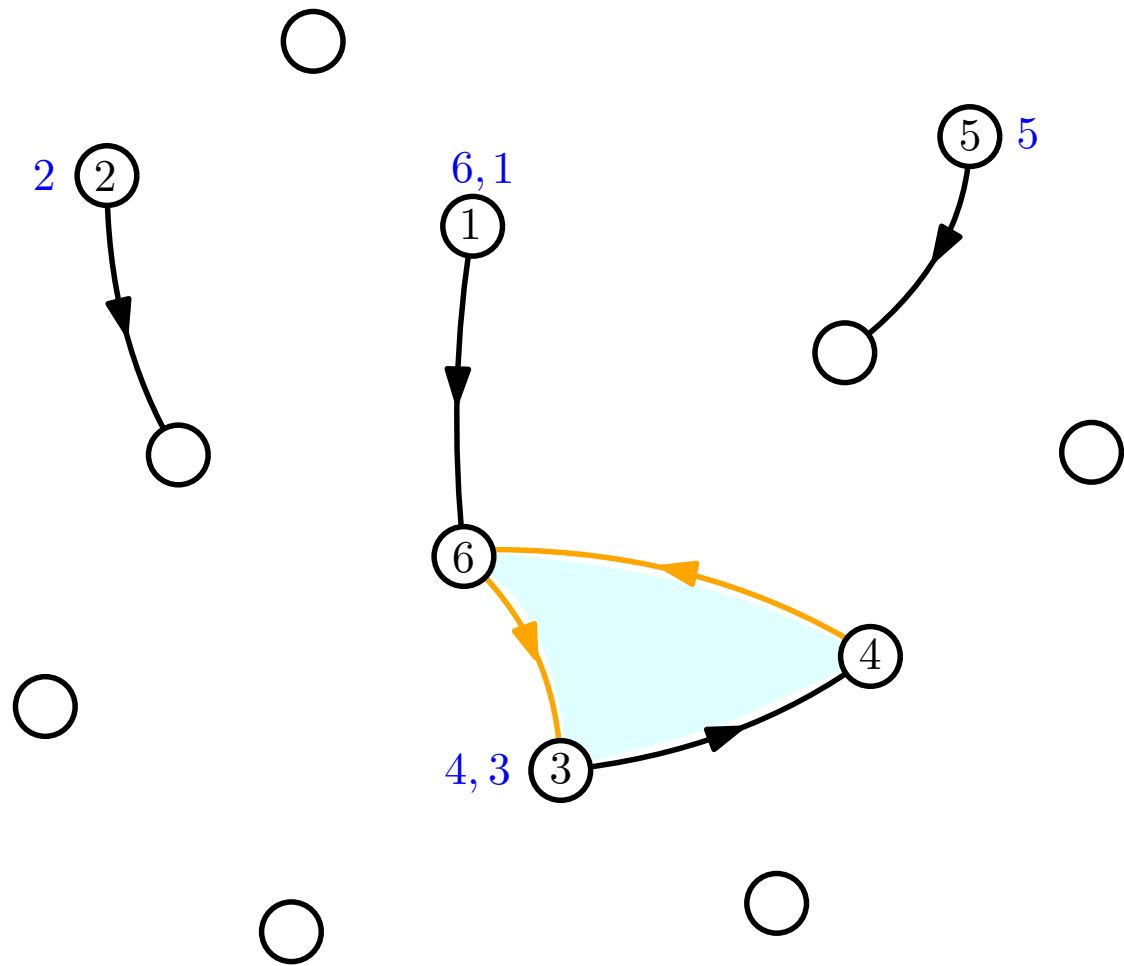


Frozen Erdős–Rényi

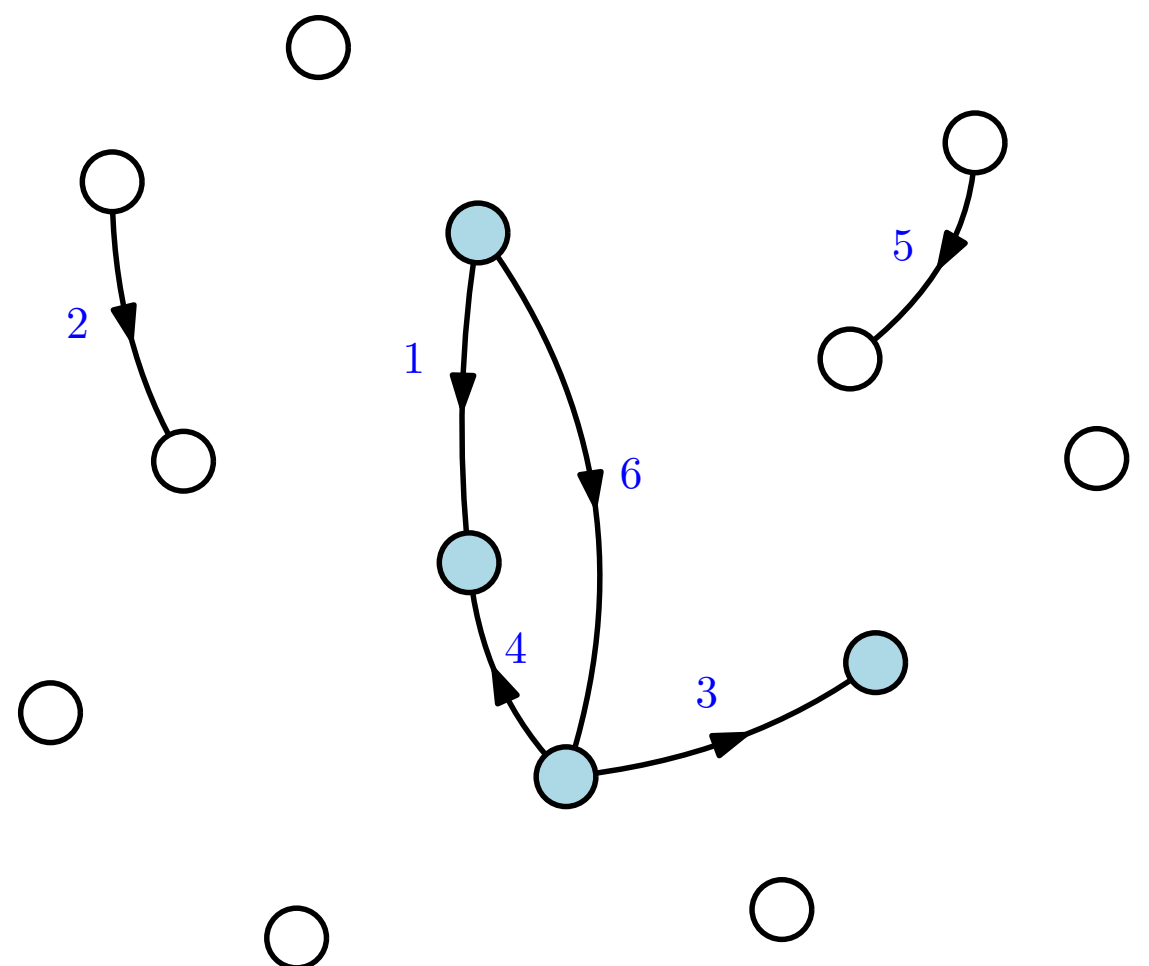


# Coupling

Parking on a mapping



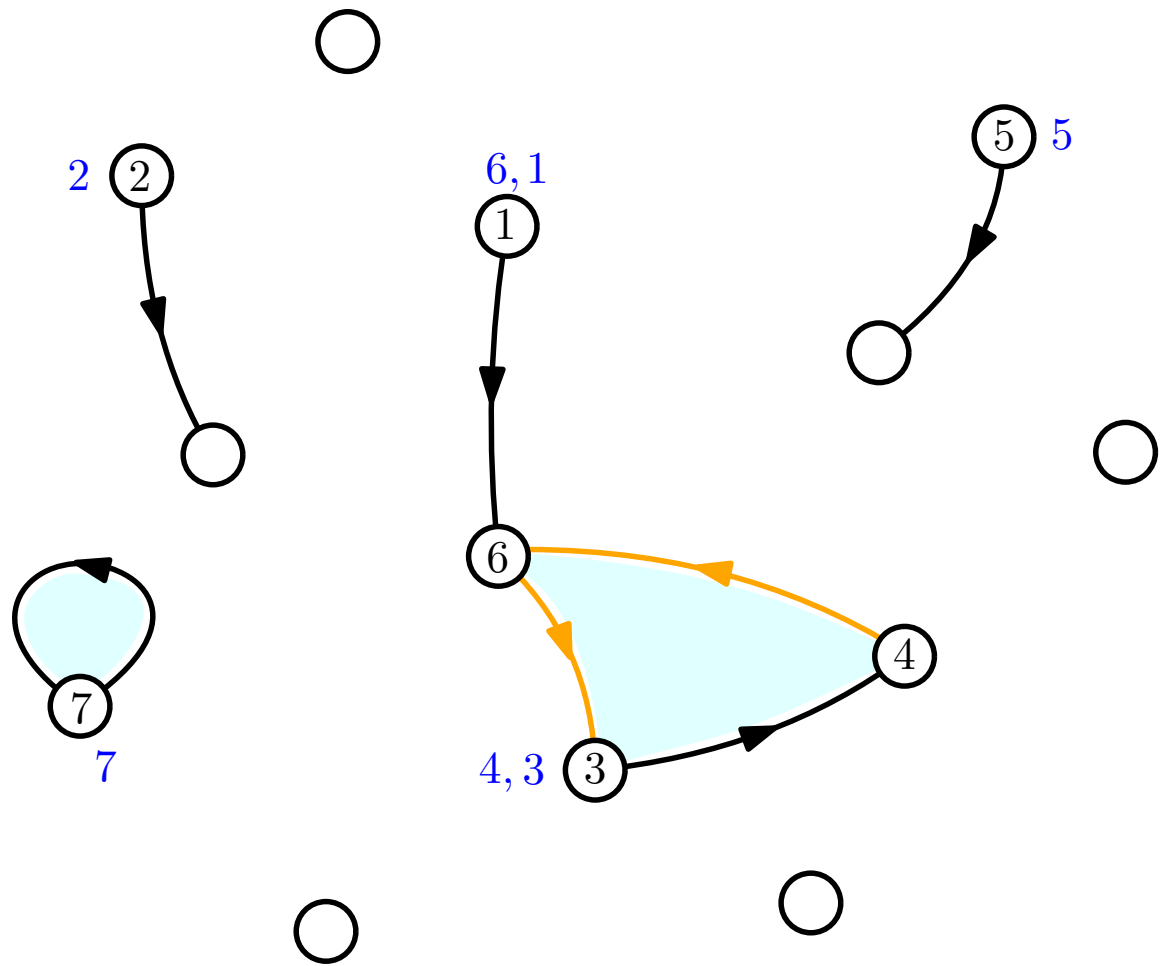
Frozen Erdős—Rényi



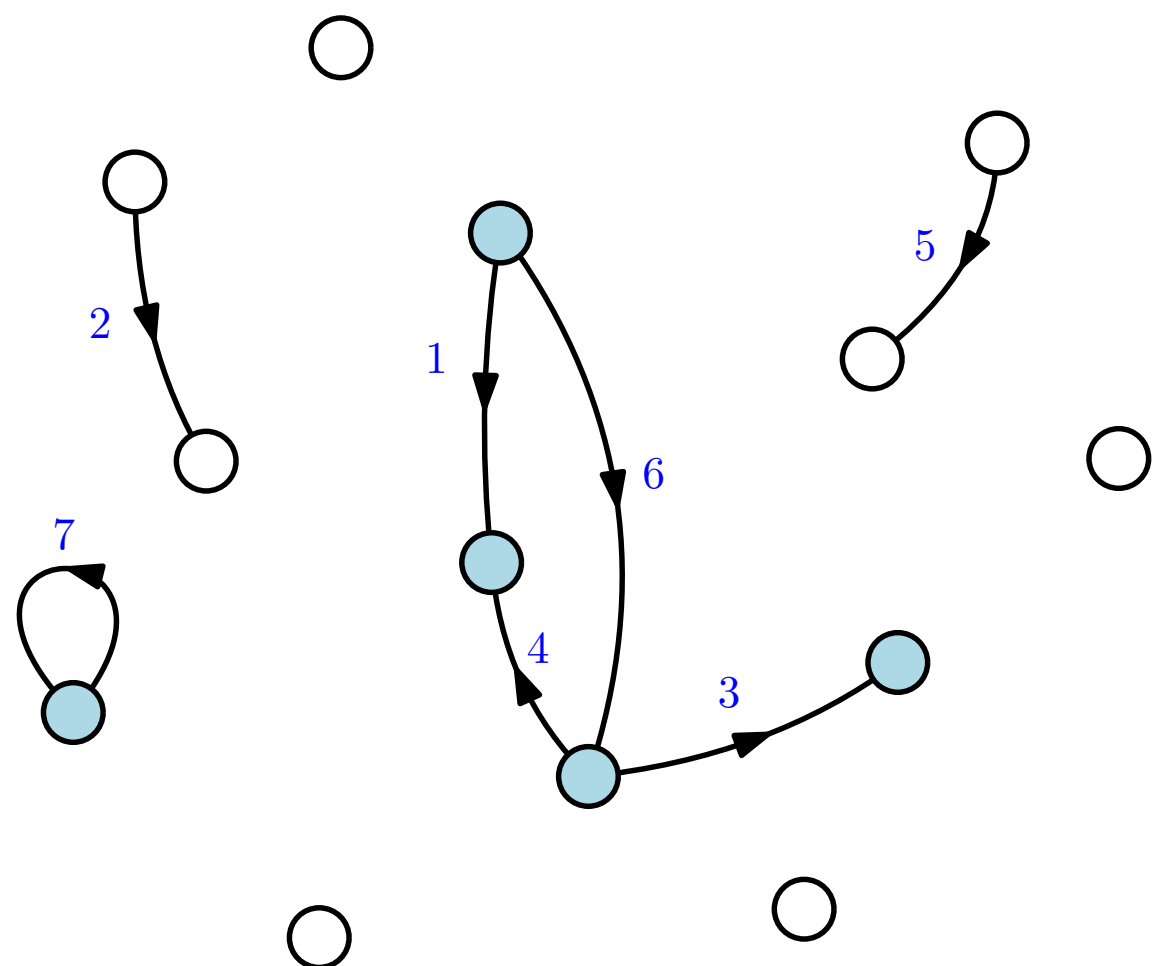


# Coupling

Parking on a mapping

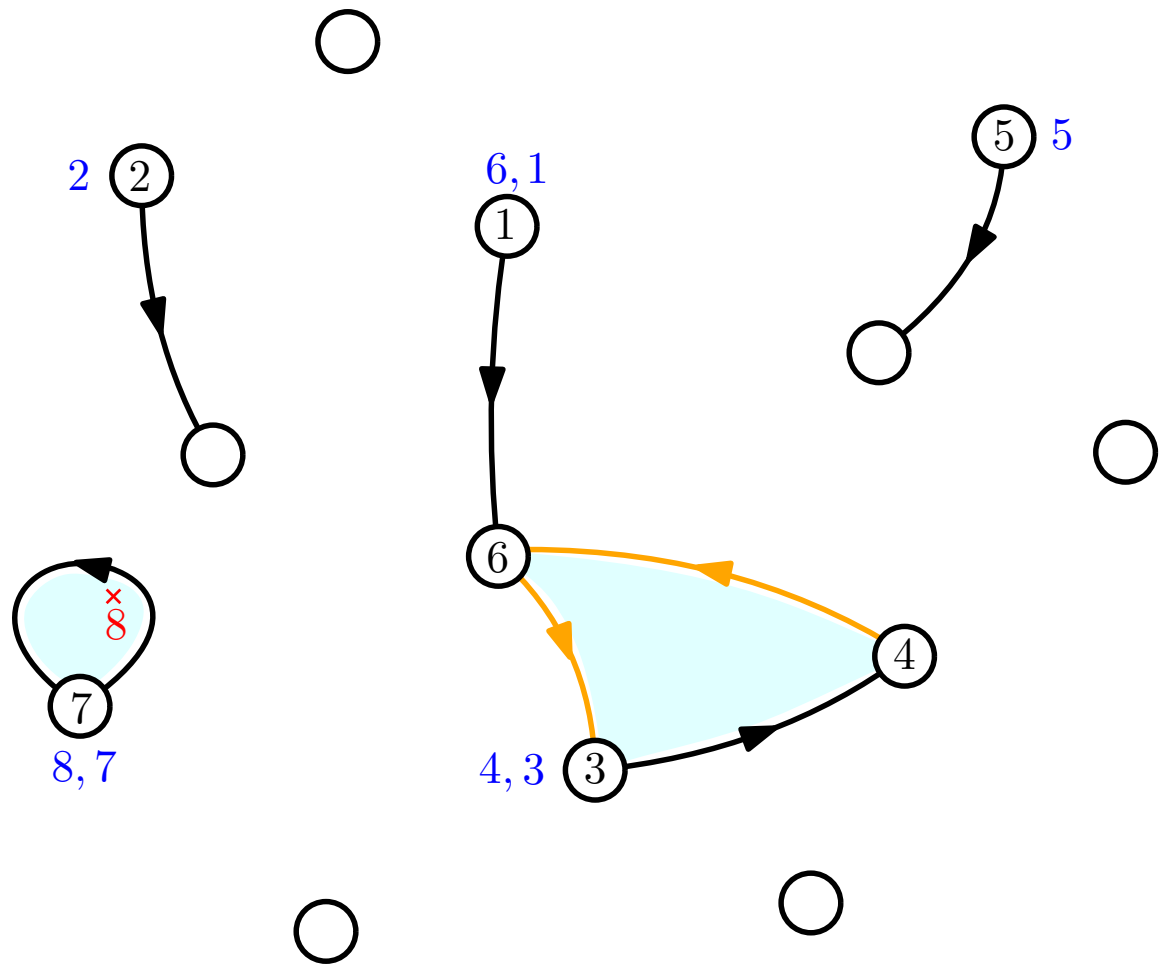


Frozen Erdős—Rényi

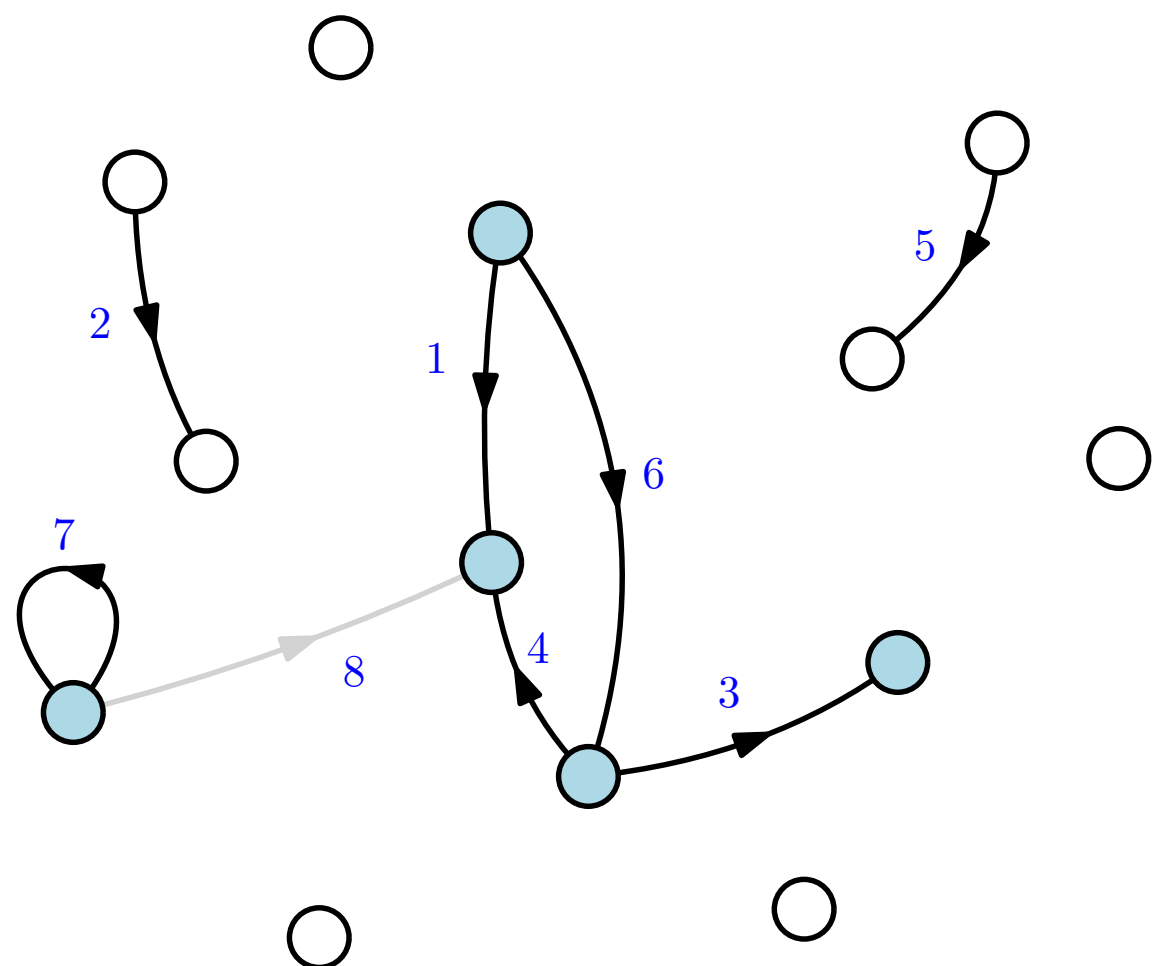


# Coupling

Parking on a mapping

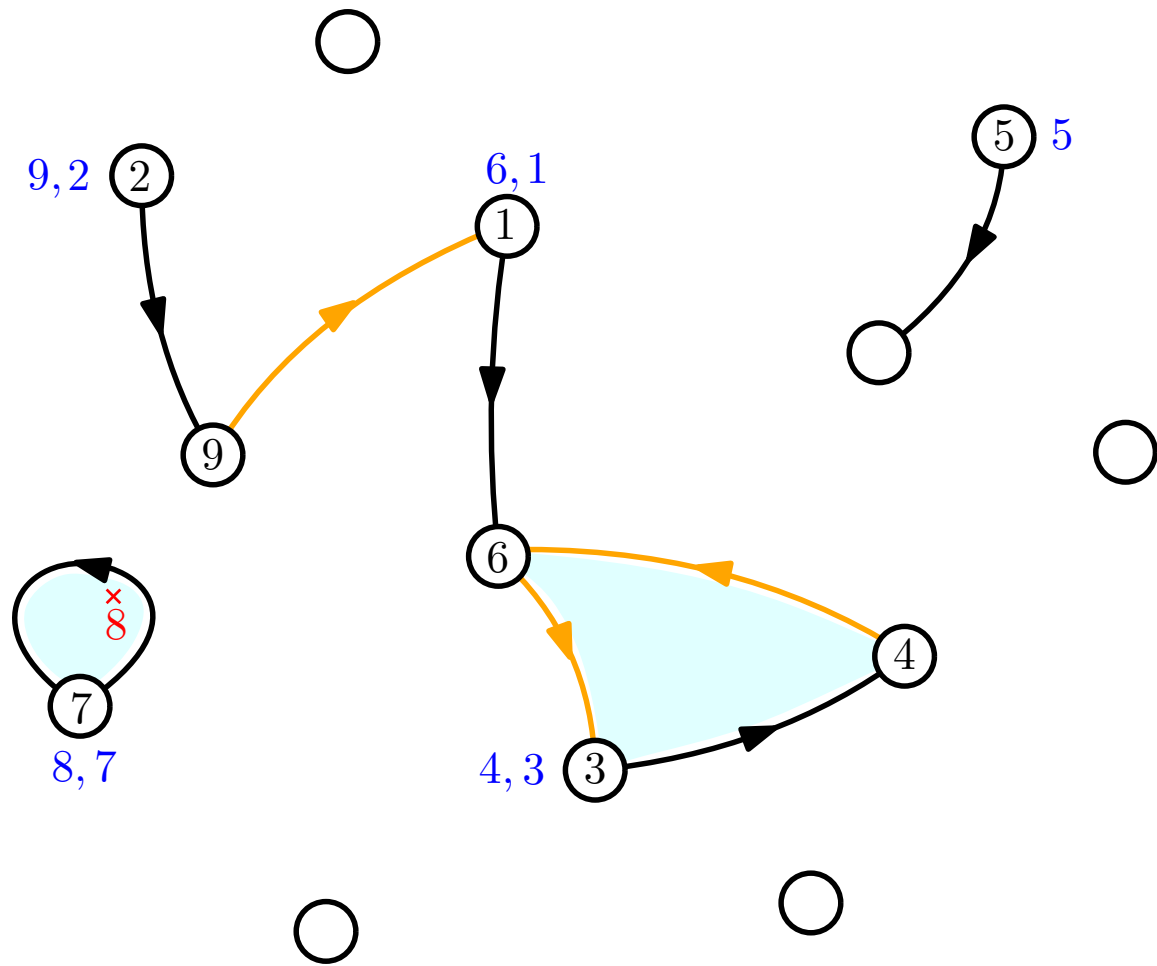


Frozen Erdős—Rényi

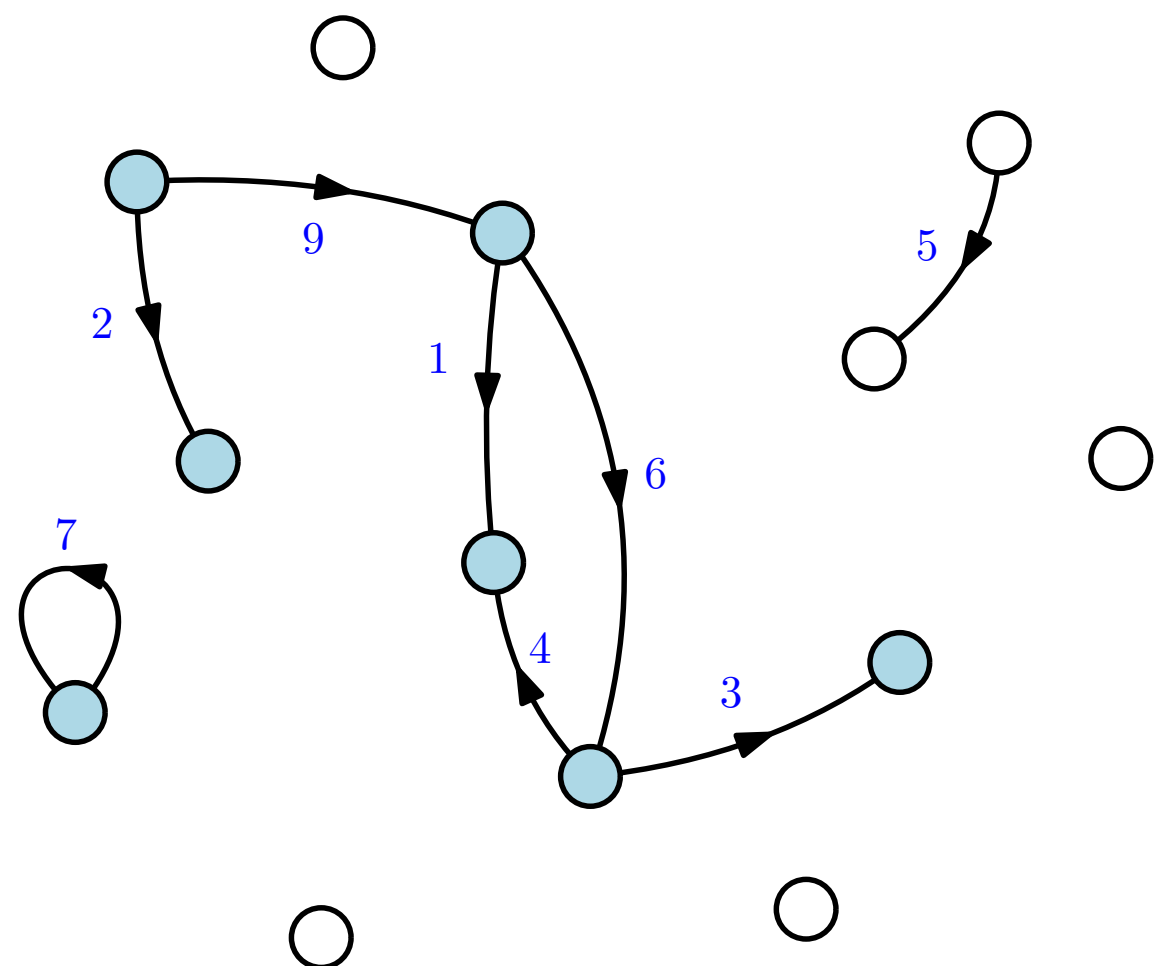


# Coupling

Parking on a mapping

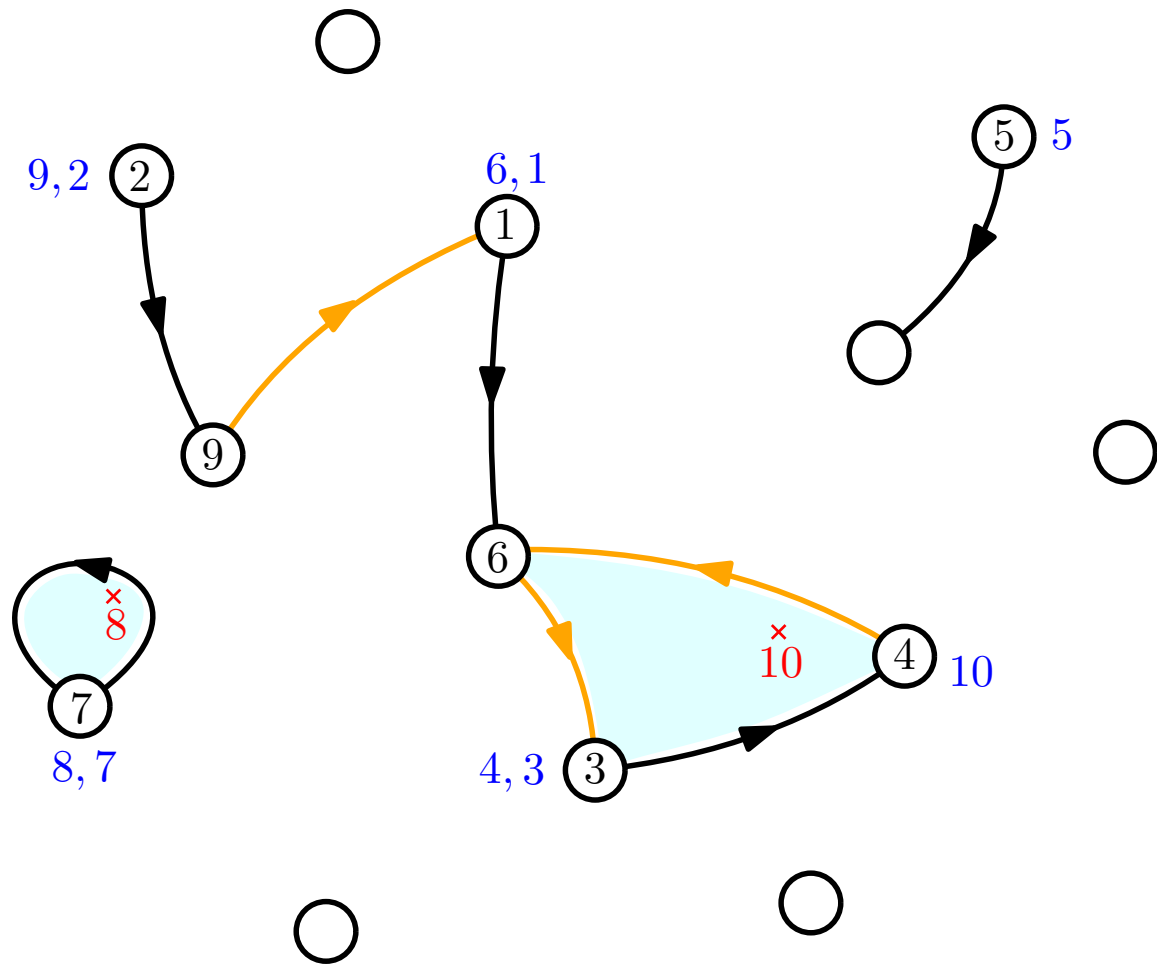


Frozen Erdős—Rényi

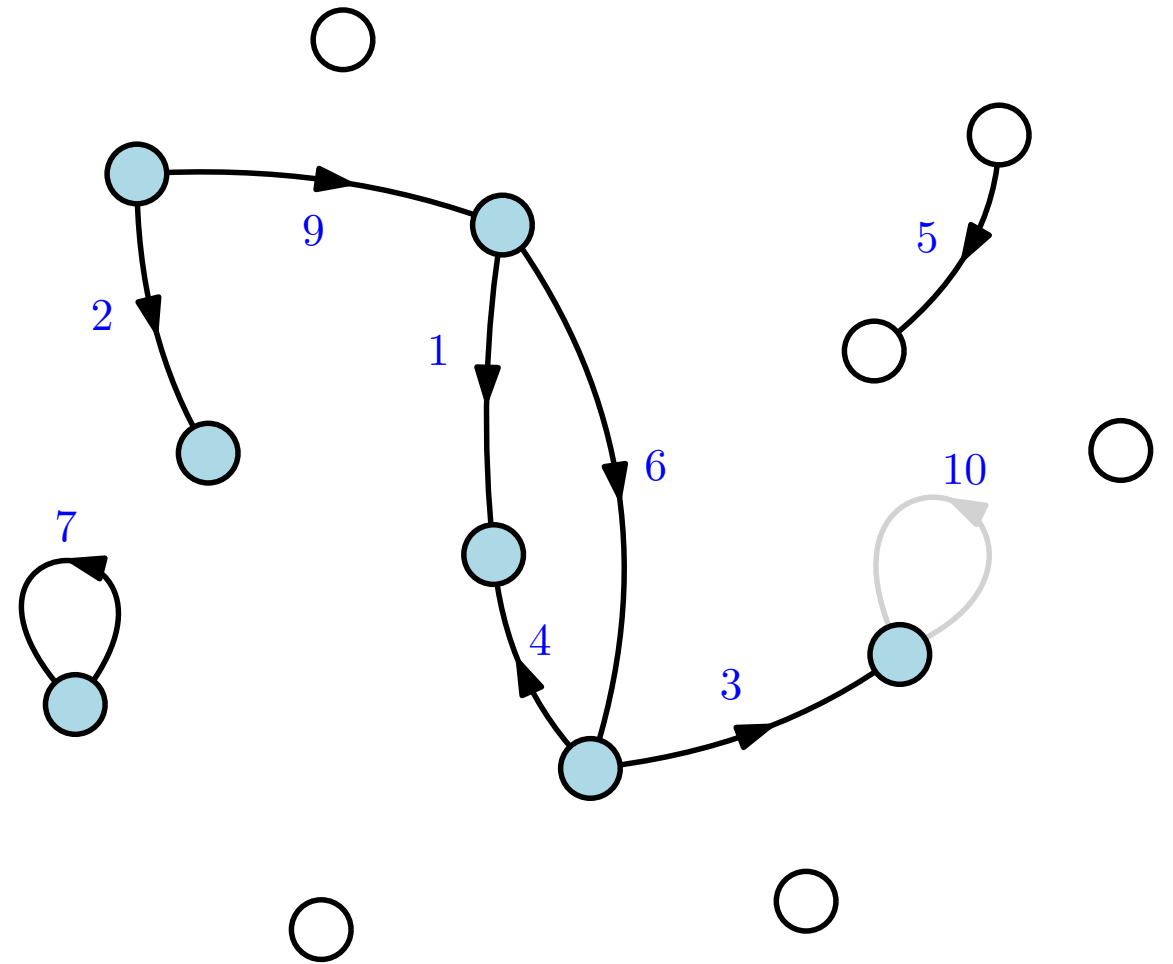


# Coupling

## Parking on a mapping

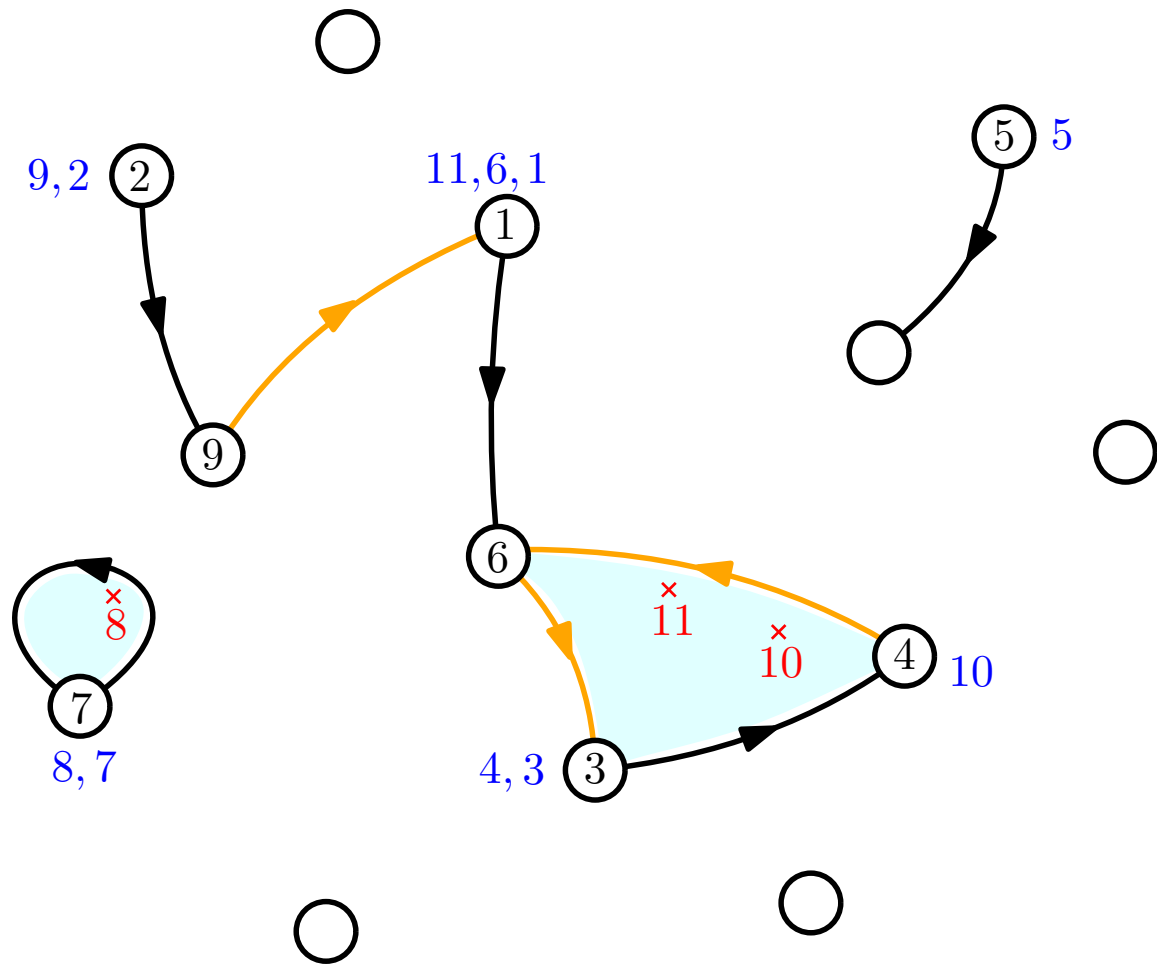


## Frozen Erdős—Rényi

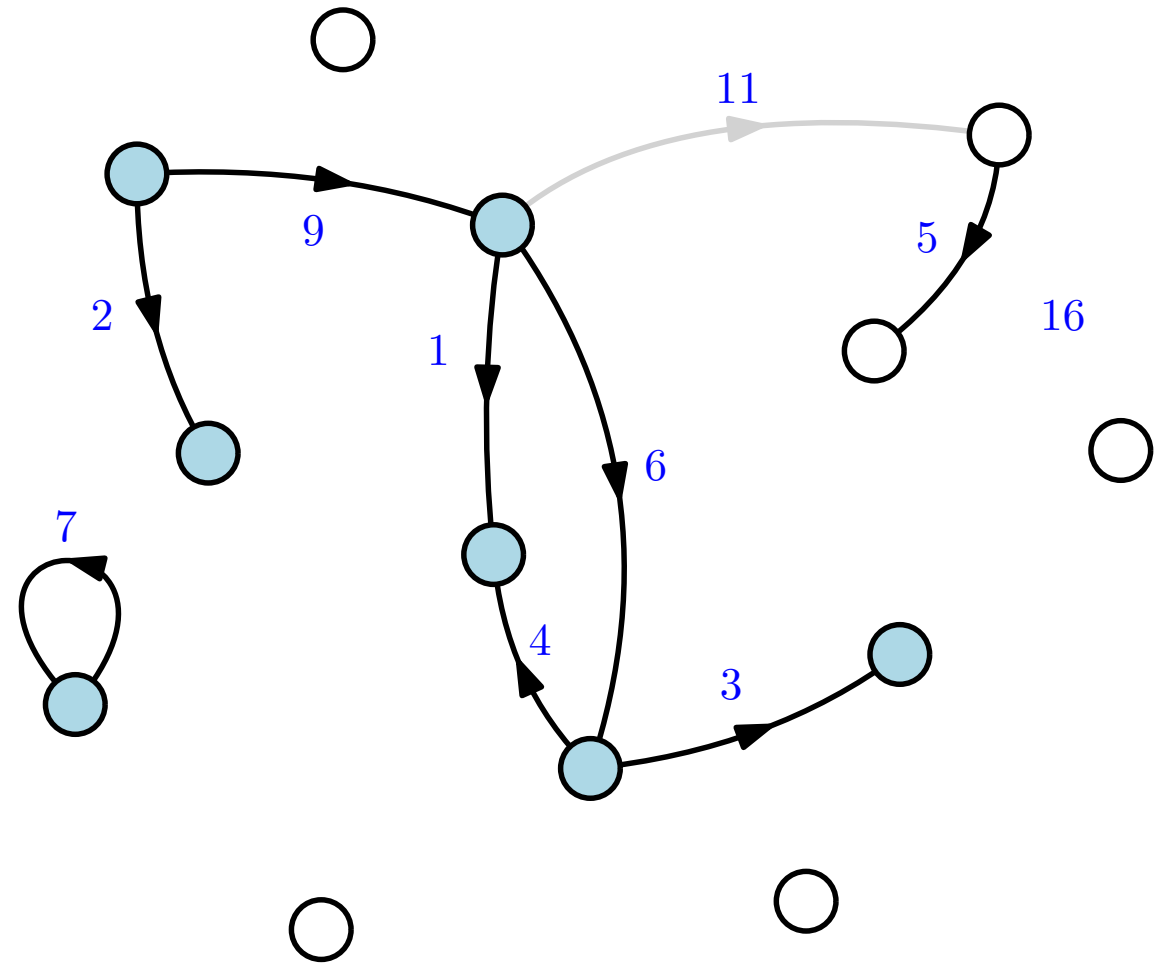


# Coupling

## Parking on a mapping



## Frozen Erdős—Rényi

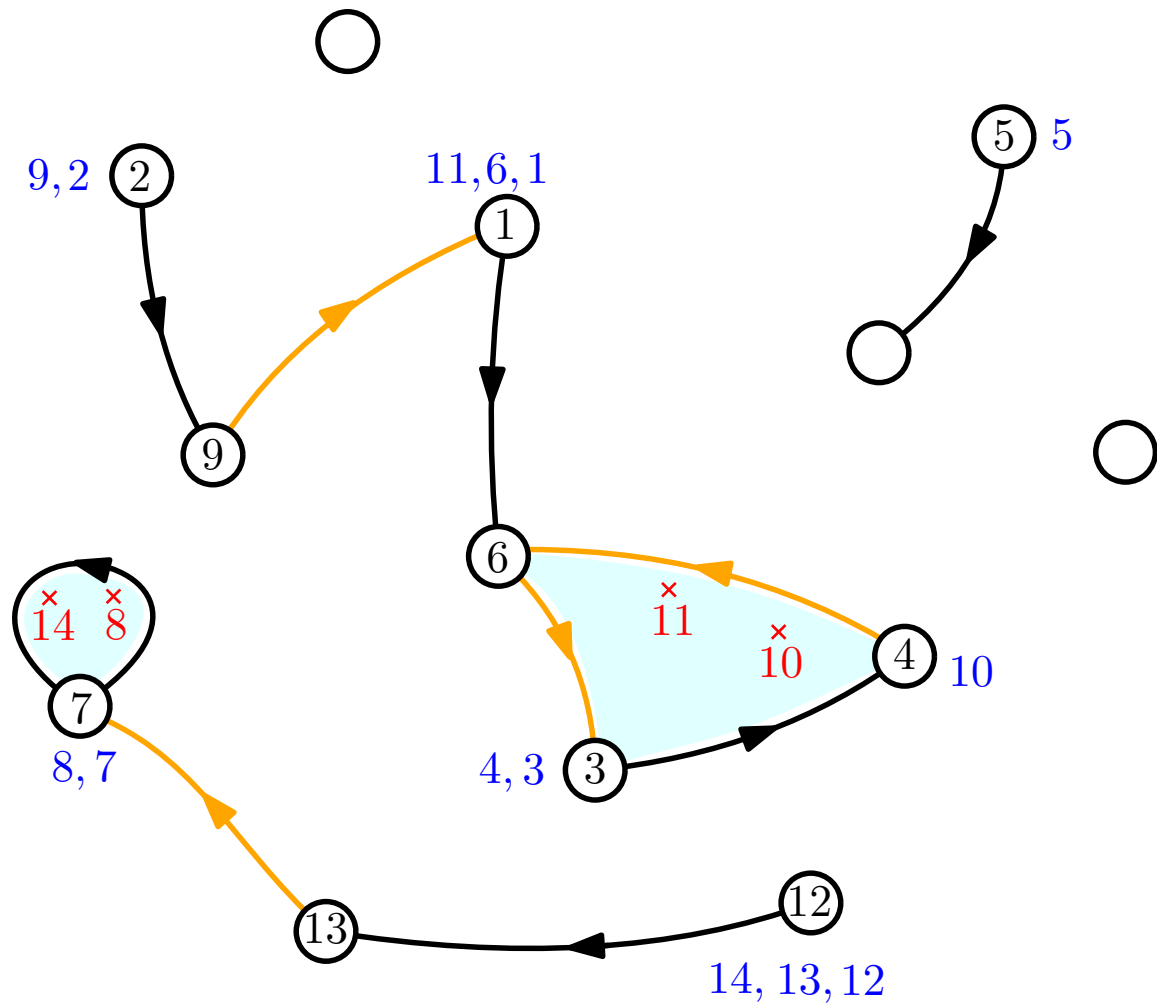




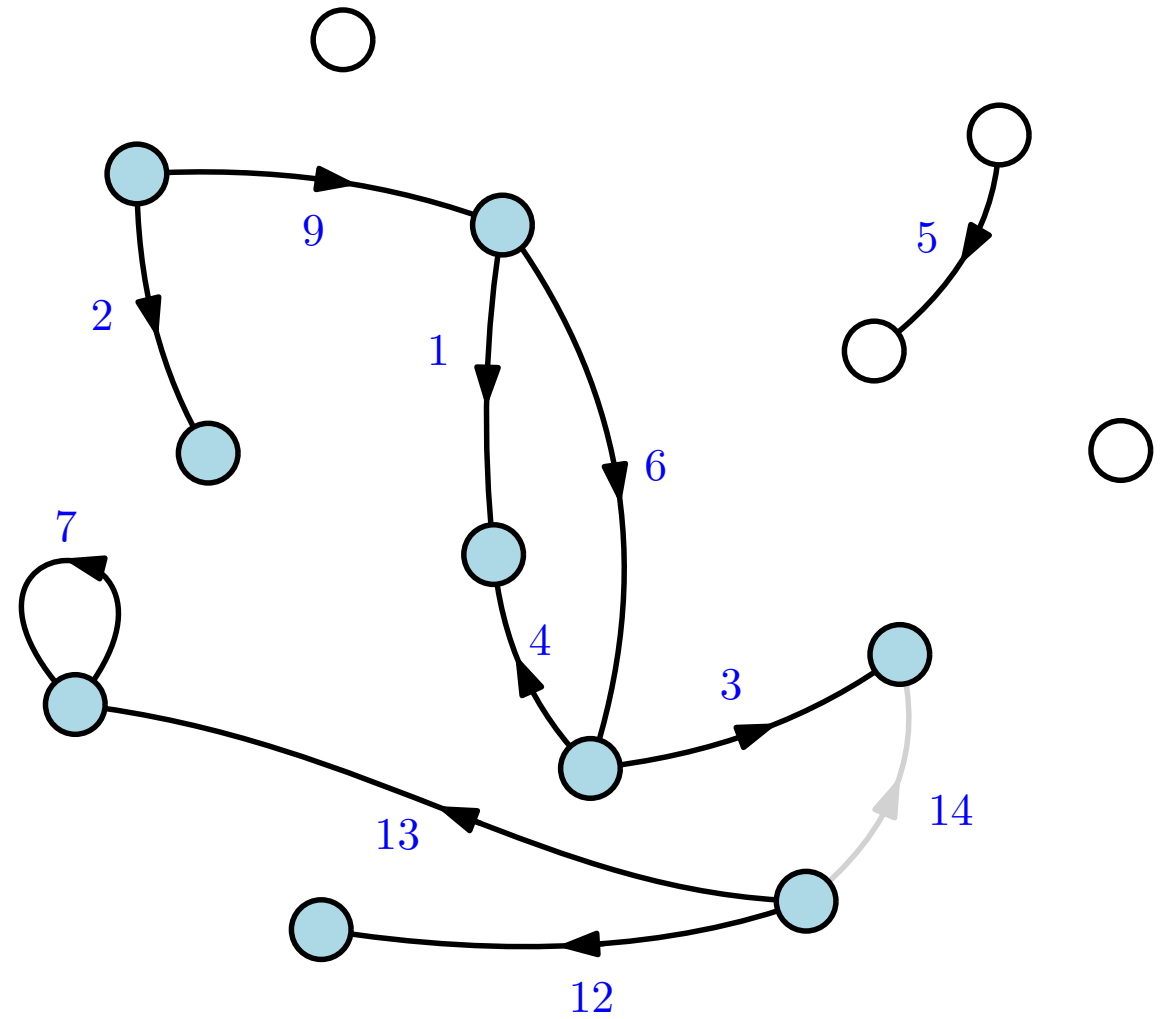


# Coupling

## Parking on a mapping



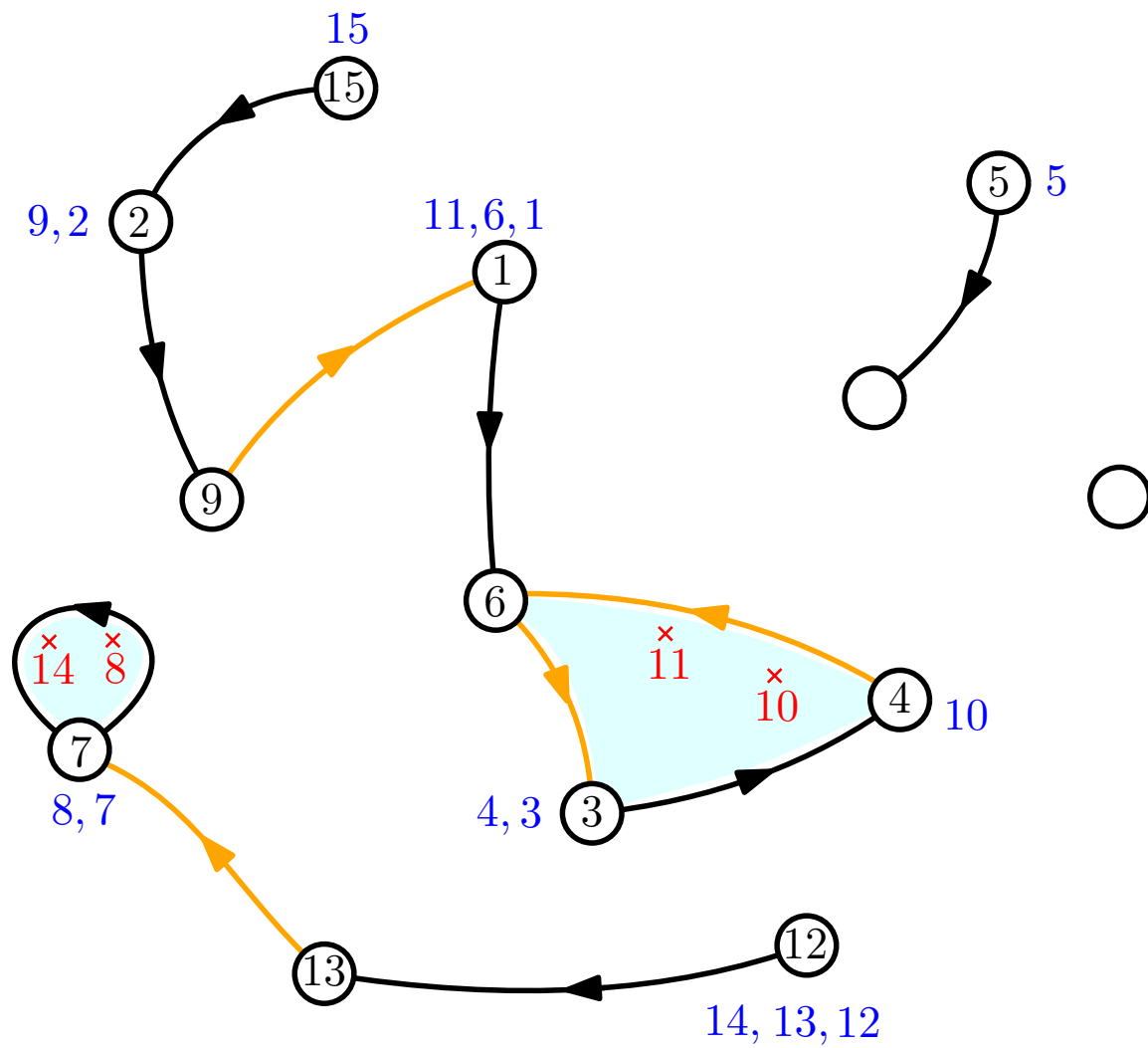
## Frozen Erdős—Rényi



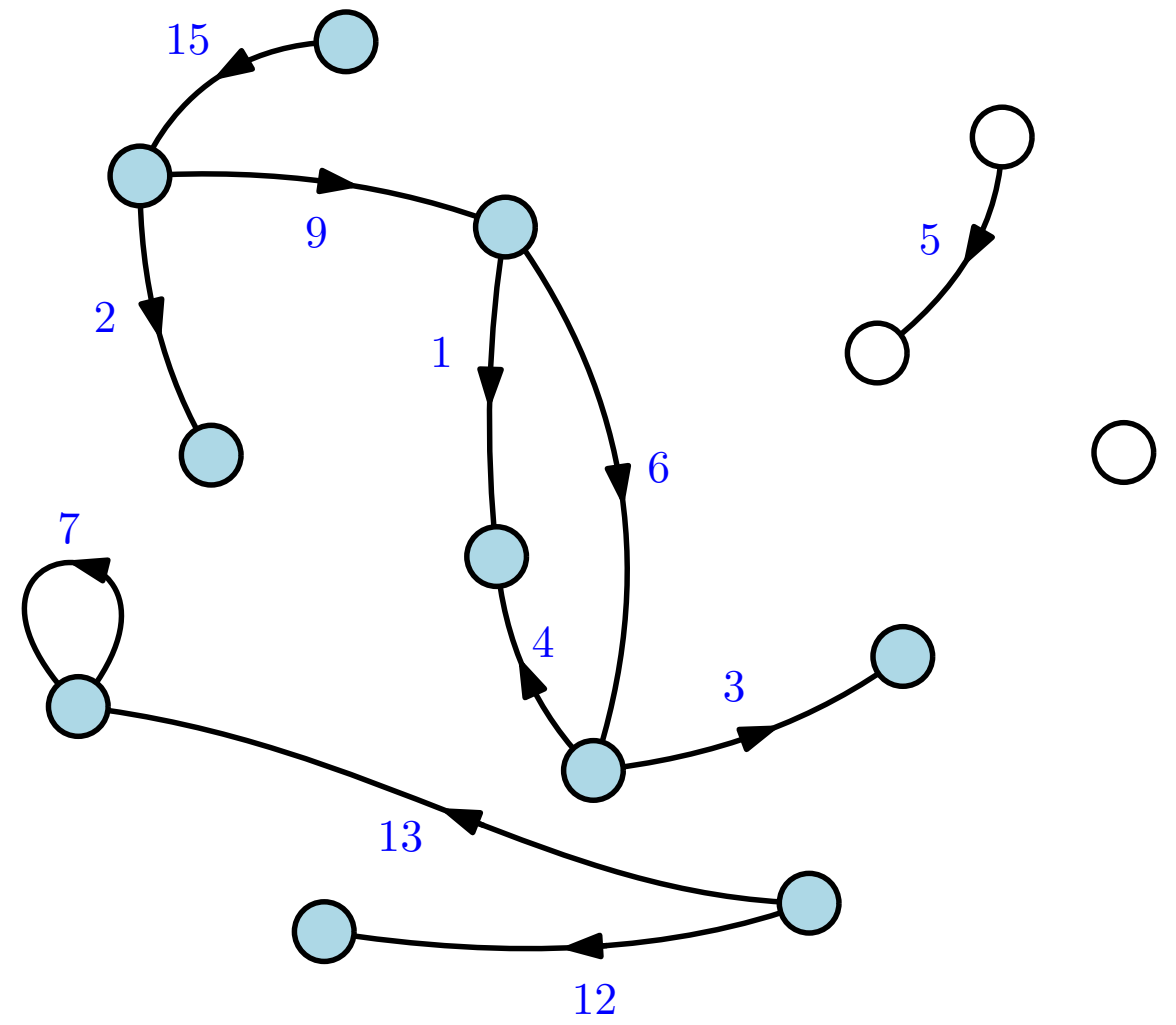


# Coupling

## Parking on a mapping

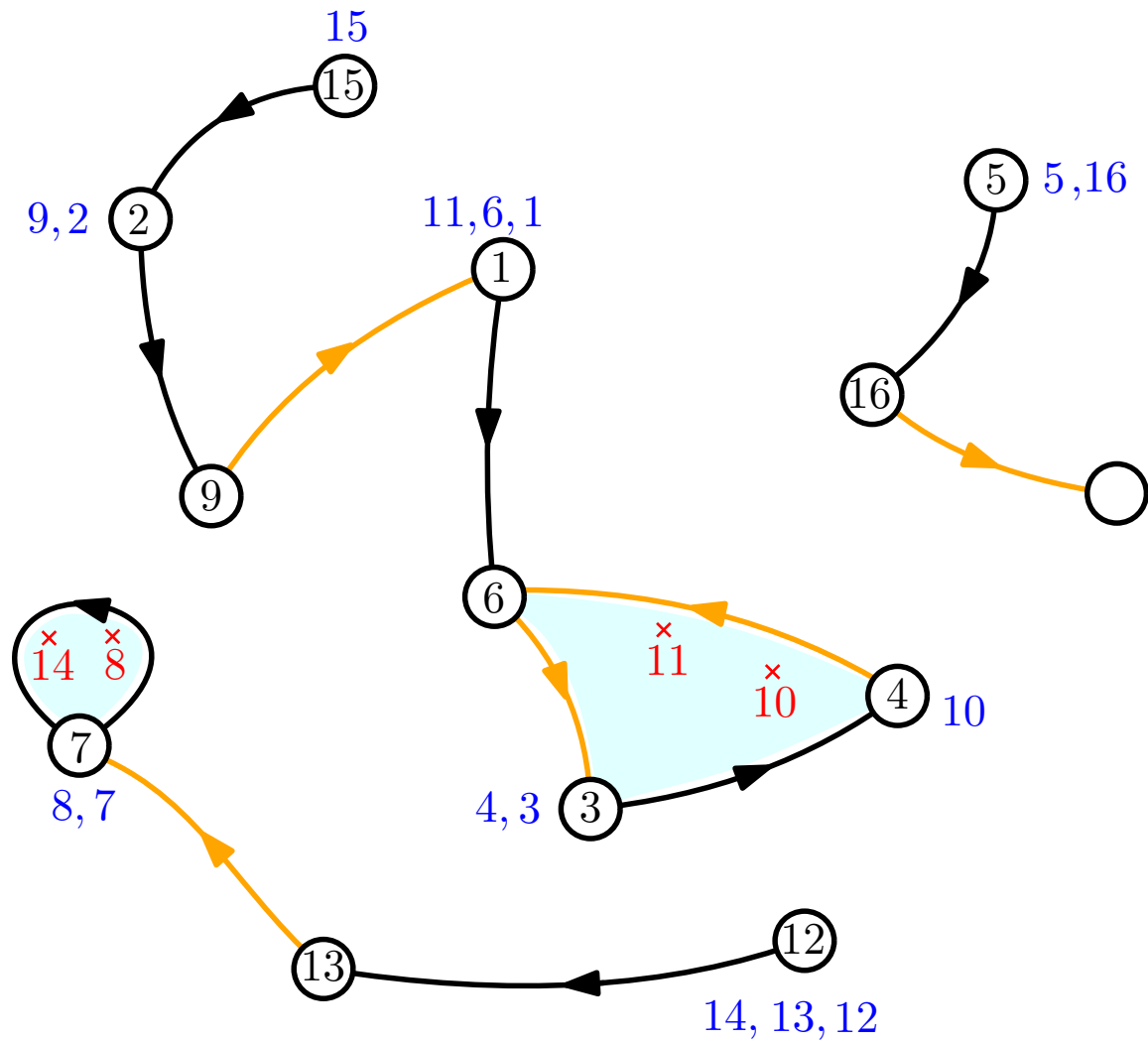


## Frozen Erdős—Rényi

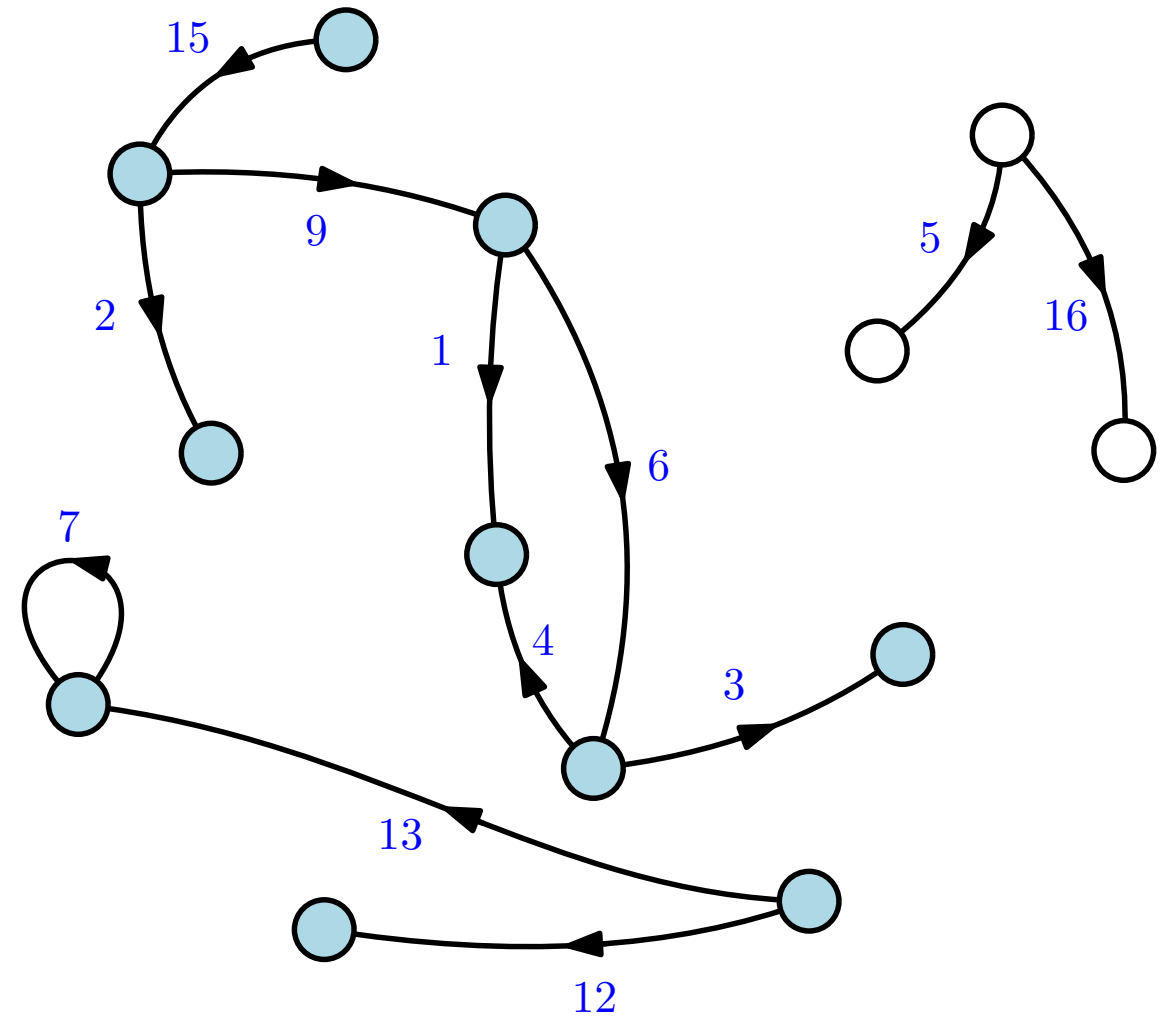


# Coupling

## Parking on a mapping

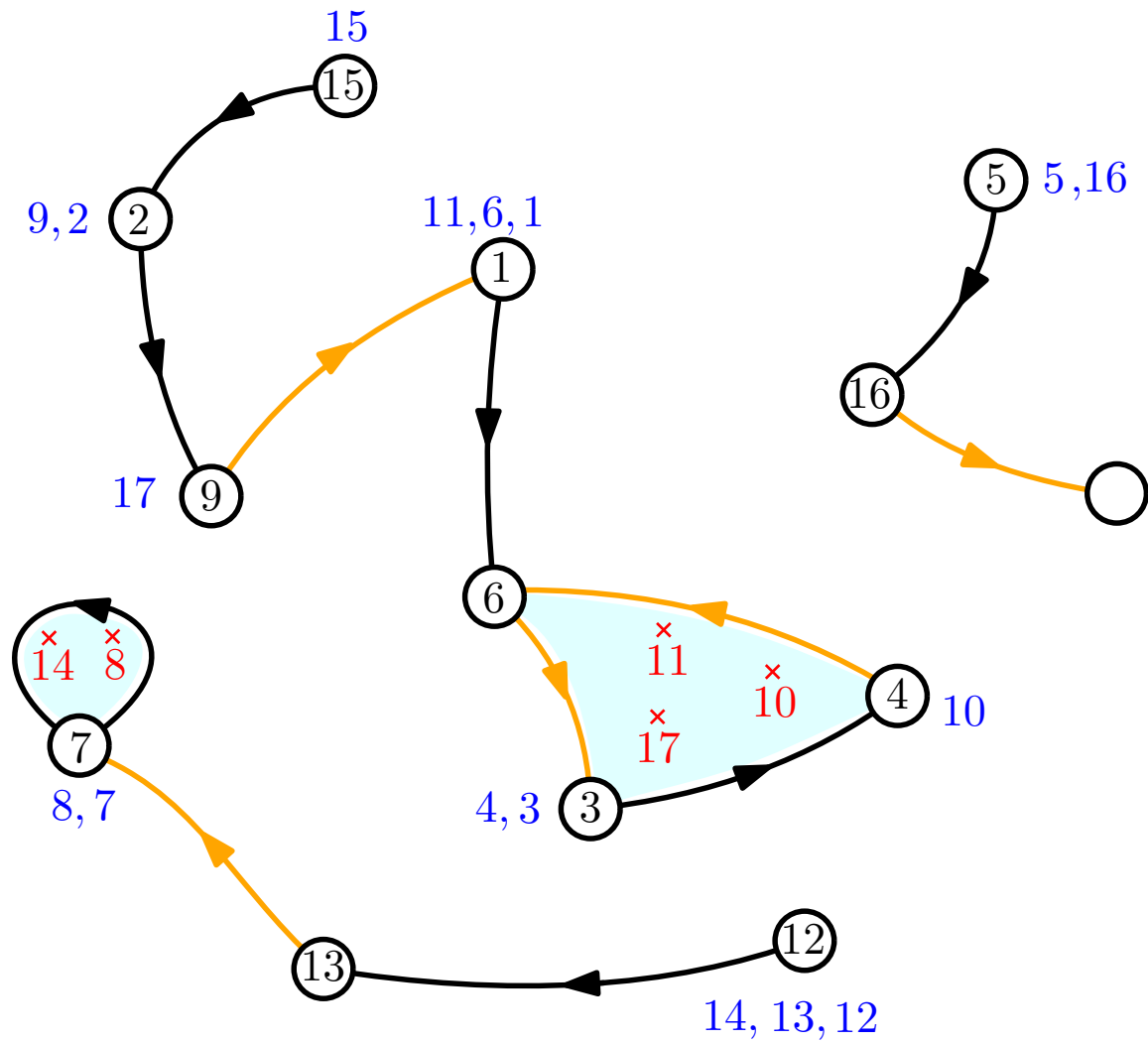


## Frozen Erdős—Rényi

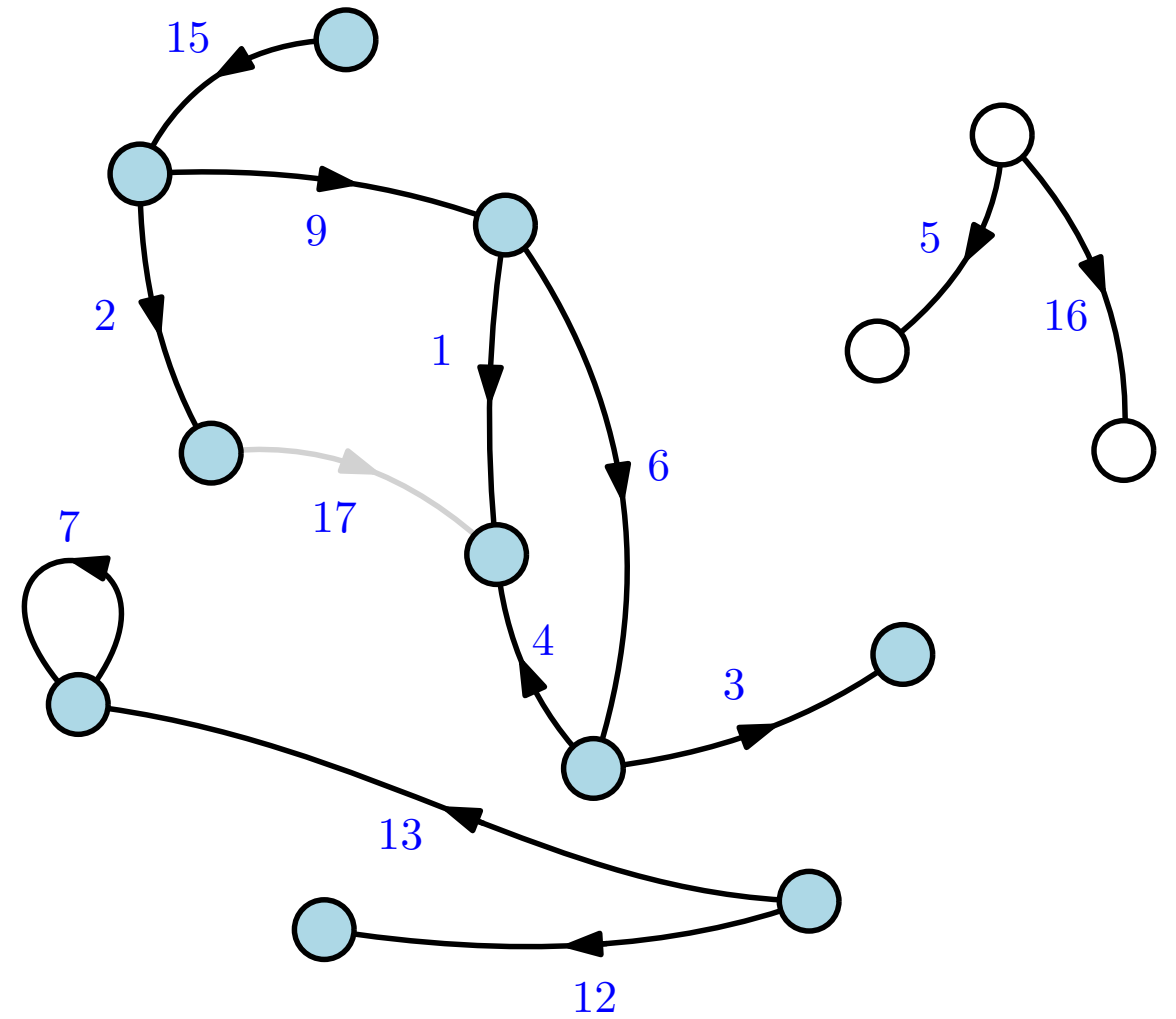


# Coupling

## Parking on a mapping



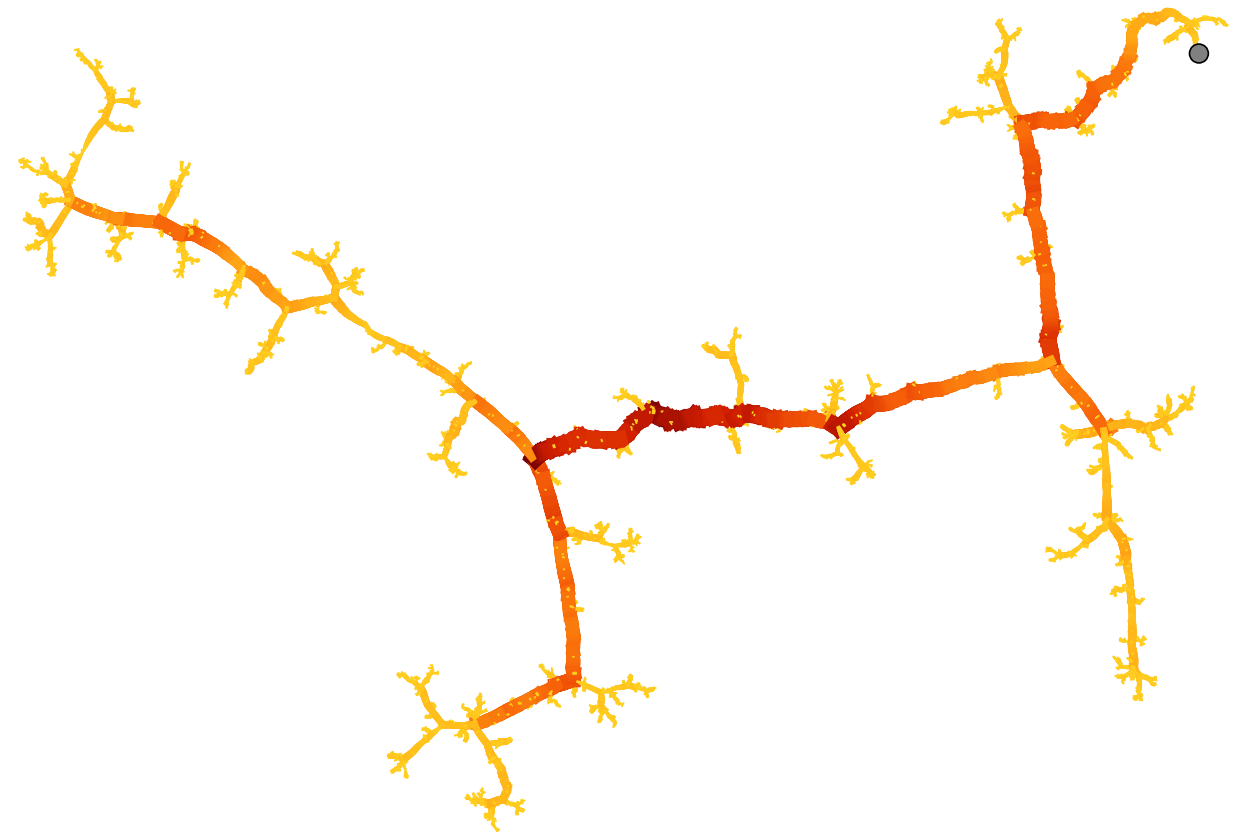
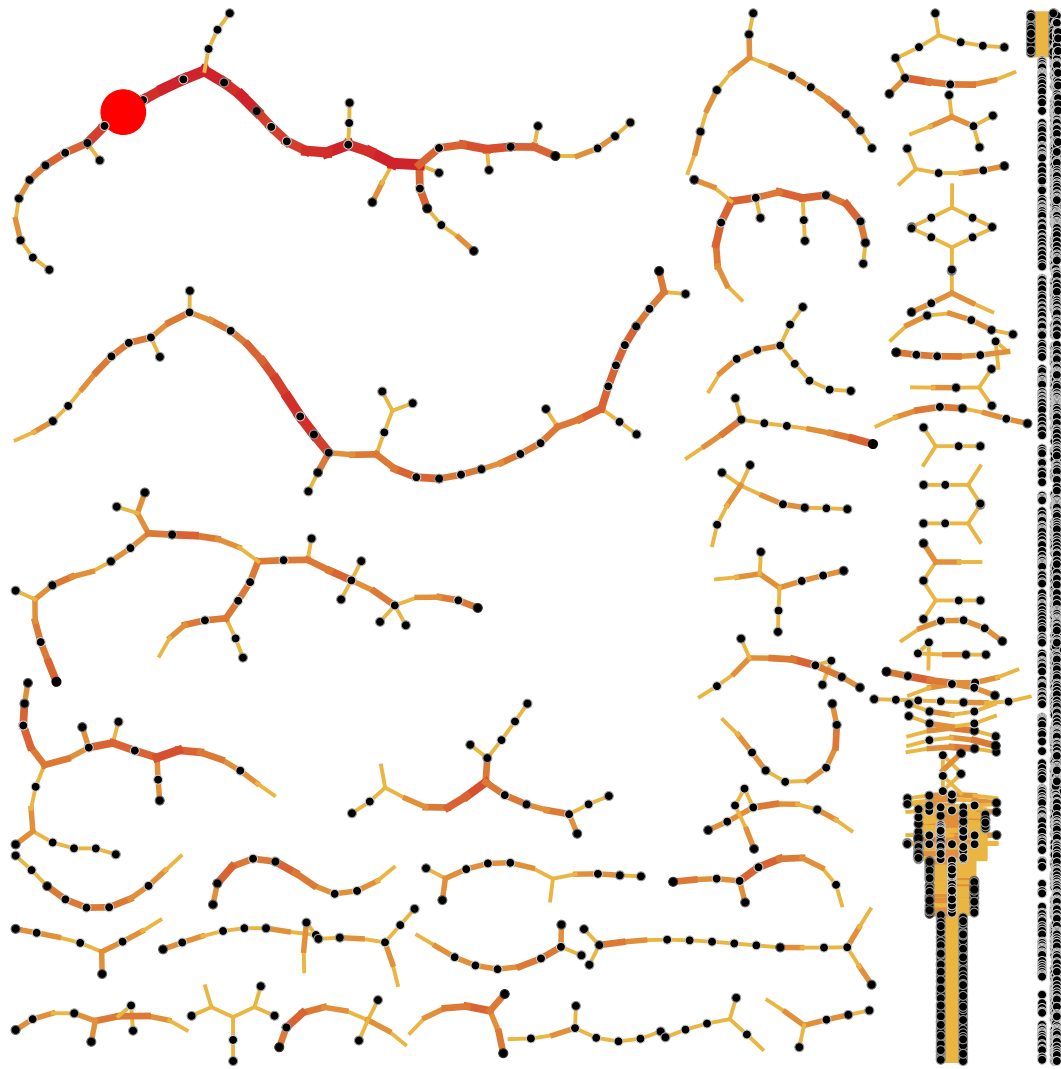
## Frozen Erdős—Rényi





# Consequences

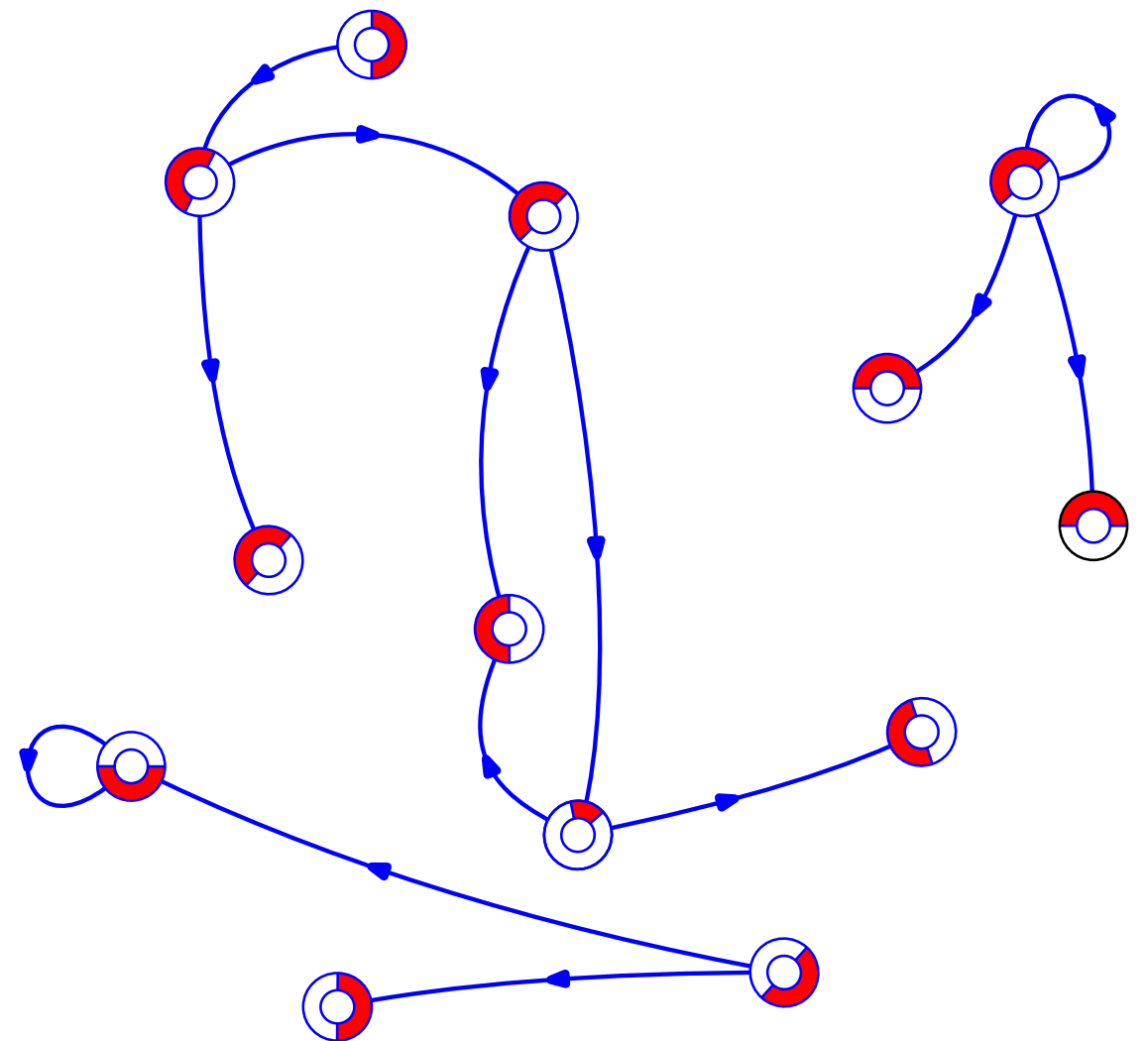
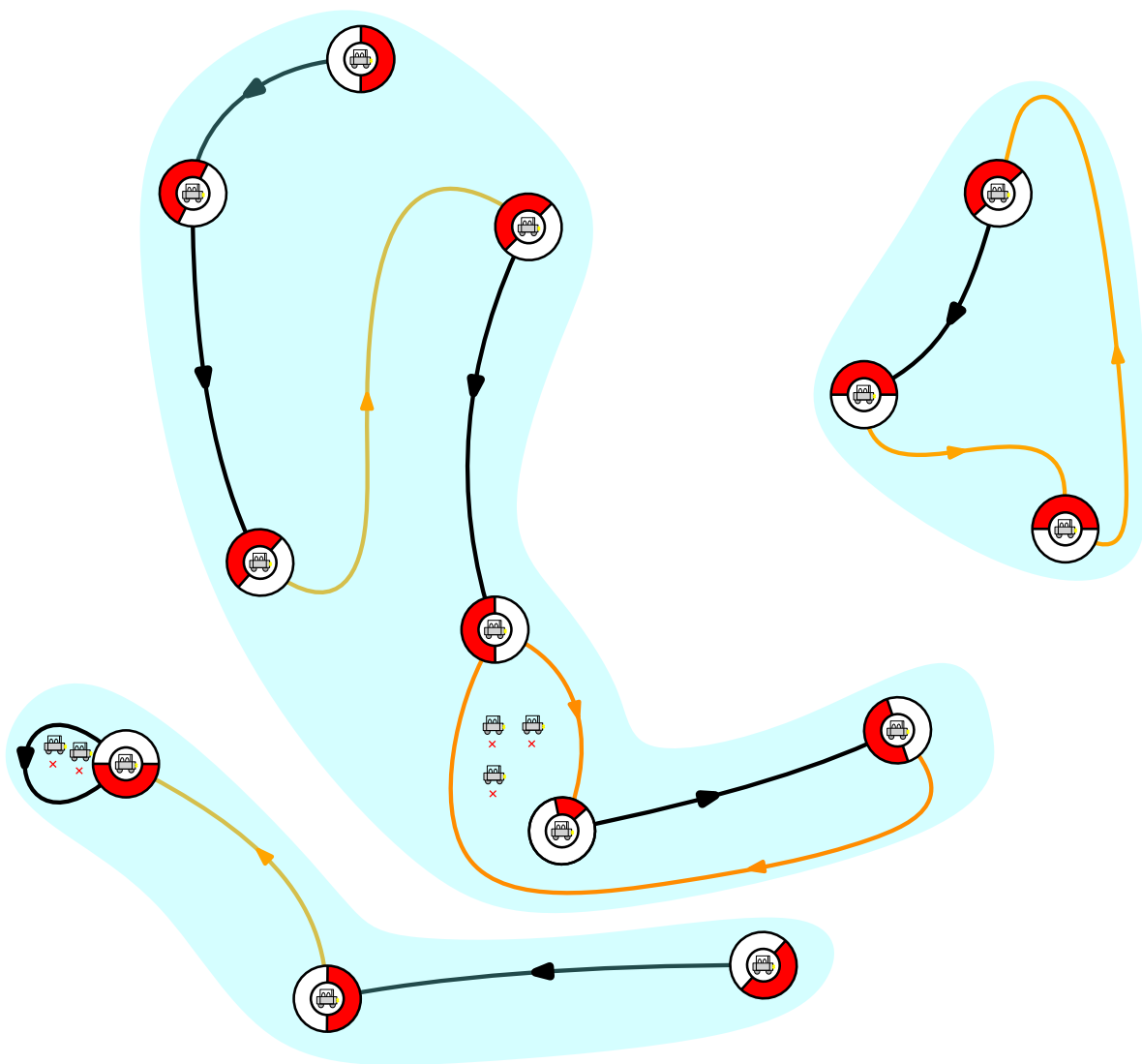
- The size of the components are the same (but not their geometry).



- $\mathbb{P} \left( \frac{n}{2} \text{ cars park on } T_n \right) \propto \mathbb{P} \left( G(n, \frac{n}{2}) \text{ has no cycle} \right) \sim \text{cst} \cdot n^{-1/6}.$

# Consequences

- Similar coupling for general Bienaymé–Galton–Watson trees and general car arrivals
- "Probabilistic" explanation of the phase transition
- Universality results



Thank you  
for your attention

